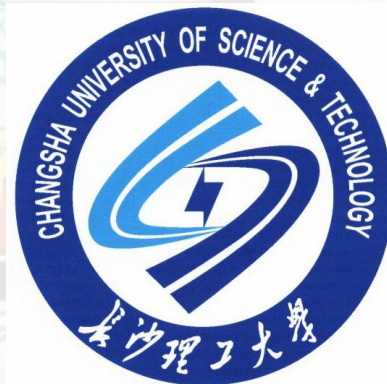


License Plate Matching Using Neural Networks



Kelvyn SOSOO (GMU)

David OUYANG (CSUST)

Mengjun WANG (CSUST)

Mentors: Lee HAN (UTK) & Kwai WONG (UTK)

Overview

- **License Plate Recognition (LPR) technology is used to gather vehicle location data**
- **Location Data includes instances of Amber Alerts, Toll Roads Speed/Travel Time, etc.**
- **The License Plate Matching (LPM) method incorporated includes a 97% match rate of vehicles, and a 60% read accuracy**
- **Programs Used: Python, Matlab**

GOAL: Raise the 60% by using Image Processing. Find a new measure to matching plate by using supervised learning.

How It Works

**Capture
images**

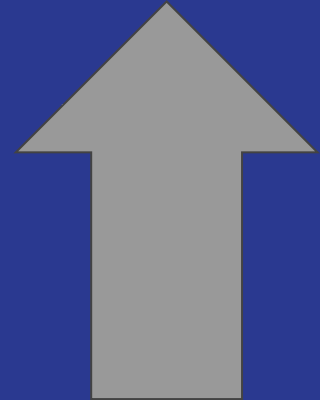
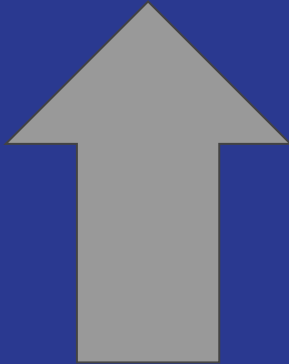


**Image
recognition**



**Plate
matching**

LPR 1



Procedure

Screen the
License
Plate images



Image Processing to
segment every
Character

Develop New
method of
matching



Neural network
training

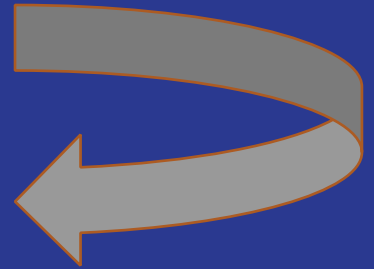
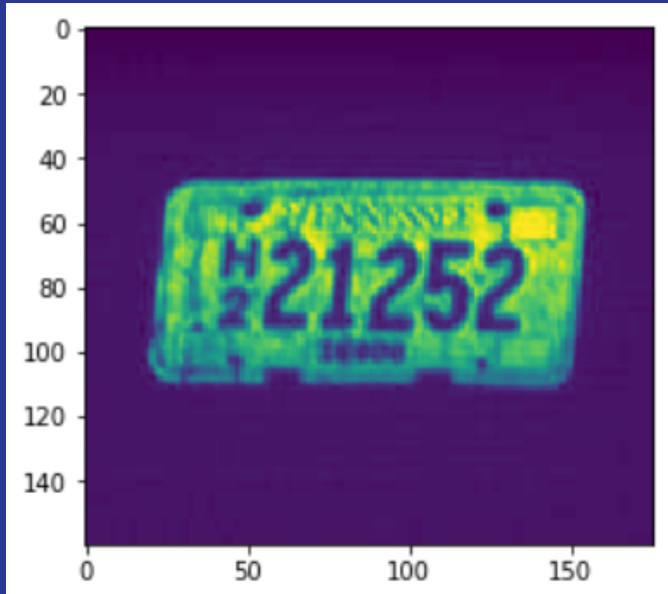


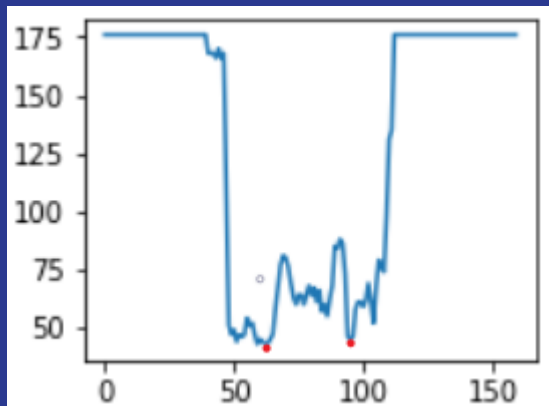
Image Processing

Step 1 : Image binarization

Method: `cv2.THRESH_OTSU`



Step 2 : Read the number of black pixels in the y direction

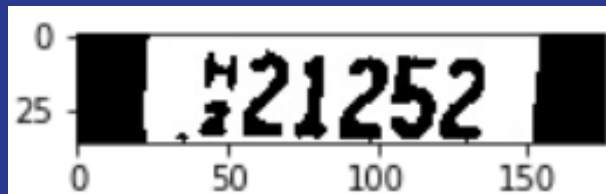


```
[176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176,
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108, 51, 47, 49, 44, 47, 46, 47, 54, 51, 52, 47, 43, 45, 44,
43, 43, 45, 47, 58, 67, 77, 81, 80, 76, 69, 63, 60, 64, 64, 60,
64, 68, 64, 67, 61, 66, 57, 60, 55, 62, 68, 85, 84, 88, 86, 73,
46, 45, 46, 58, 61, 61, 59, 62, 69, 61, 52, 68, 79, 76, 74, 98,
131, 135, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176,
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176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176,
176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176, 176,
176, 176]
```

```
np.argmin(row_nz[0 : floor(len(row_nz)/2)]) == 59
np.argmin(row_nz[floor(len(row_nz)/2) : ]) == 95
```

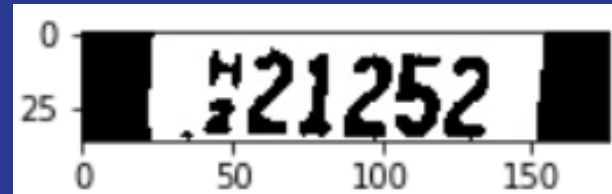
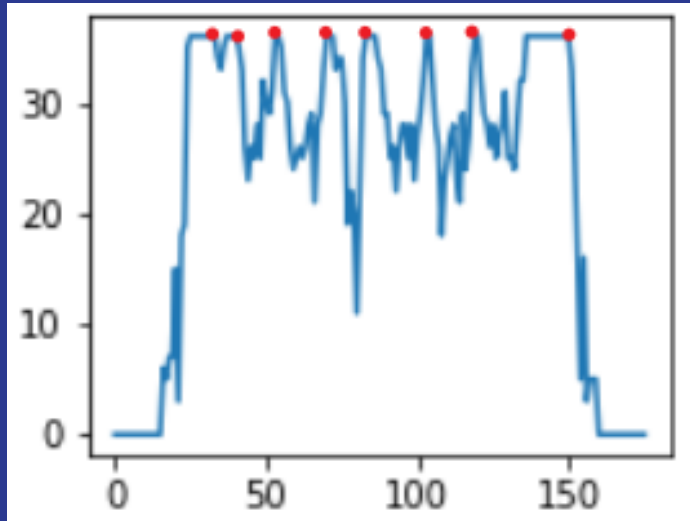
```
row_nz(59) = 43
row_nz(95) = 45
```

(59, 43) (95,45)

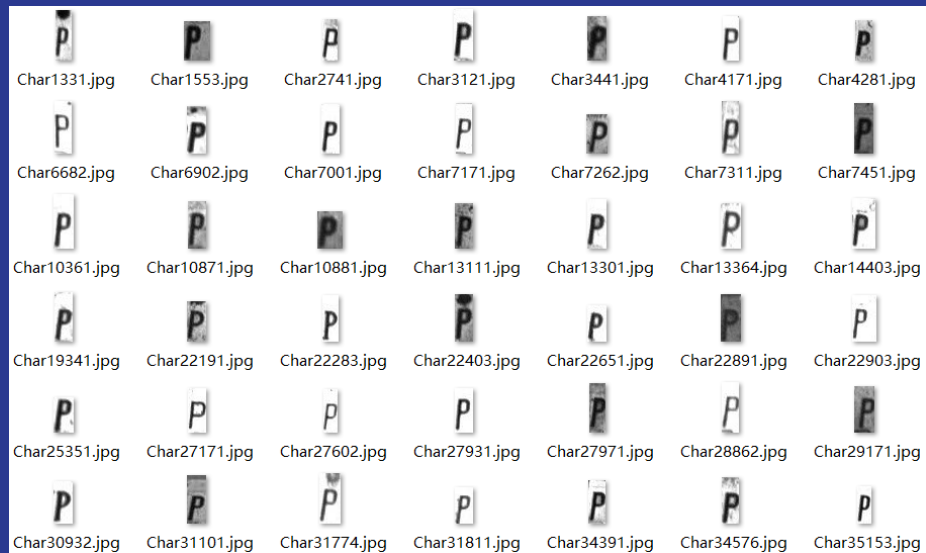


Step 3 : Read the number of white pixels in the x direction

KEY POINT & CUT POINT : [33, 40, 54, 72, 86, 104, 120, 150]



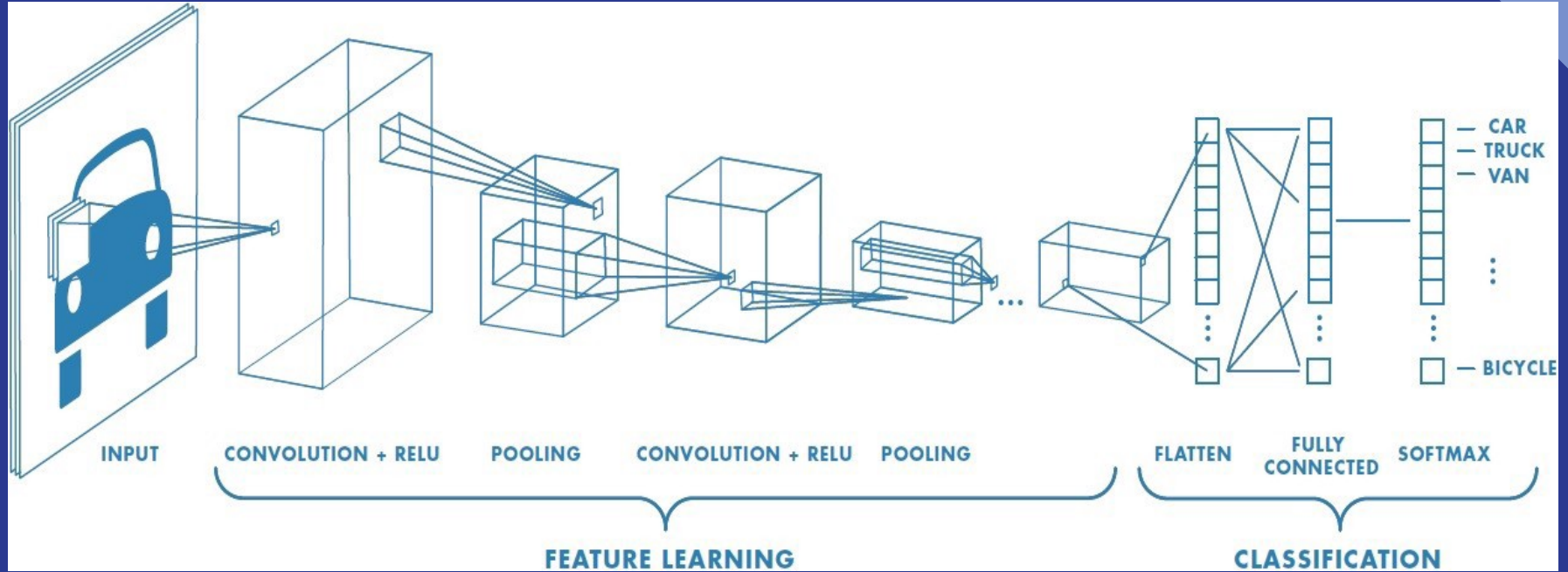
Final Outcome



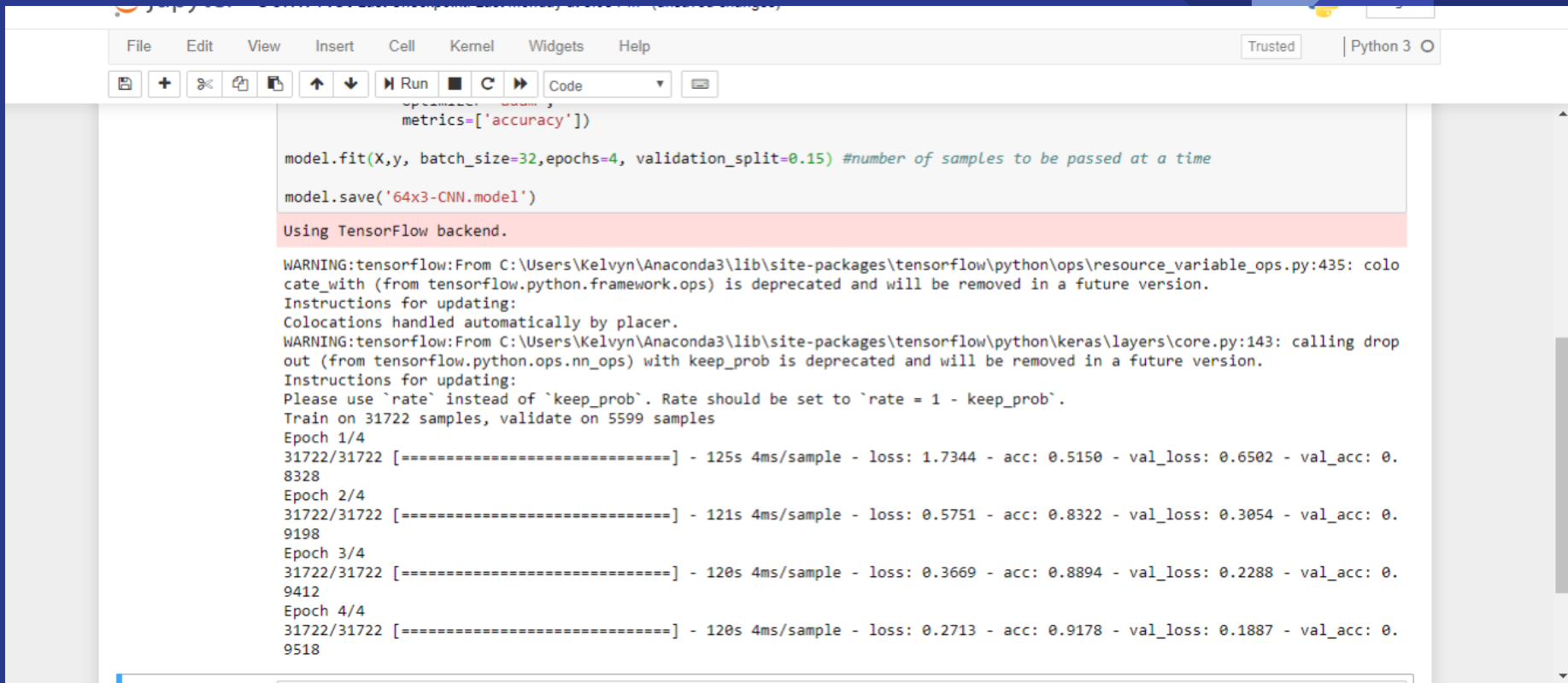
Supervised Learning: Neural Network

- Previous slide presented the outcome of Character Segmentation
 - It is very time consuming to transfer the characters to the proper label/category
- Instead of spending countless hours manually moving files, Data Augmentation was implemented
- Categories included A-Z and 0-9

Convolutional Neural Networks



Performance



```
metrics=['accuracy'])

model.fit(X,y, batch_size=32,epochs=4, validation_split=0.15) #number of samples to be passed at a time

model.save('64x3-CNN.model')

Using TensorFlow backend.

WARNING:tensorflow:From C:\Users\Kelvyn\Anaconda3\lib\site-packages\tensorflow\python\ops\resource_variable_ops.py:435: colocate_with (from tensorflow.python.framework.ops) is deprecated and will be removed in a future version.
Instructions for updating:
Colocations handled automatically by placer.
WARNING:tensorflow:From C:\Users\Kelvyn\Anaconda3\lib\site-packages\tensorflow\python\keras\layers\core.py:143: calling drop_out (from tensorflow.python.ops.nn_ops) with keep_prob is deprecated and will be removed in a future version.
Instructions for updating:
Please use `rate` instead of `keep_prob`. Rate should be set to `rate = 1 - keep_prob`.
Train on 31722 samples, validate on 5599 samples
Epoch 1/4
31722/31722 [=====] - 125s 4ms/sample - loss: 1.7344 - acc: 0.5150 - val_loss: 0.6502 - val_acc: 0.8328
Epoch 2/4
31722/31722 [=====] - 121s 4ms/sample - loss: 0.5751 - acc: 0.8322 - val_loss: 0.3054 - val_acc: 0.9198
Epoch 3/4
31722/31722 [=====] - 120s 4ms/sample - loss: 0.3669 - acc: 0.8894 - val_loss: 0.2288 - val_acc: 0.9412
Epoch 4/4
31722/31722 [=====] - 120s 4ms/sample - loss: 0.2713 - acc: 0.9178 - val_loss: 0.1887 - val_acc: 0.9518
```

- After four epochs, the model was able to reach a validation accuracy of 95.18%

Next Step

- Think of a way to store License Plates with this method
- Find way to string together characters for Matching step

Plate Matching

Ex: the tag of a license plate is **4455HZ**
LPR 1 reads the plate as **44S5H2**,
LPR2 is **4455HZ**

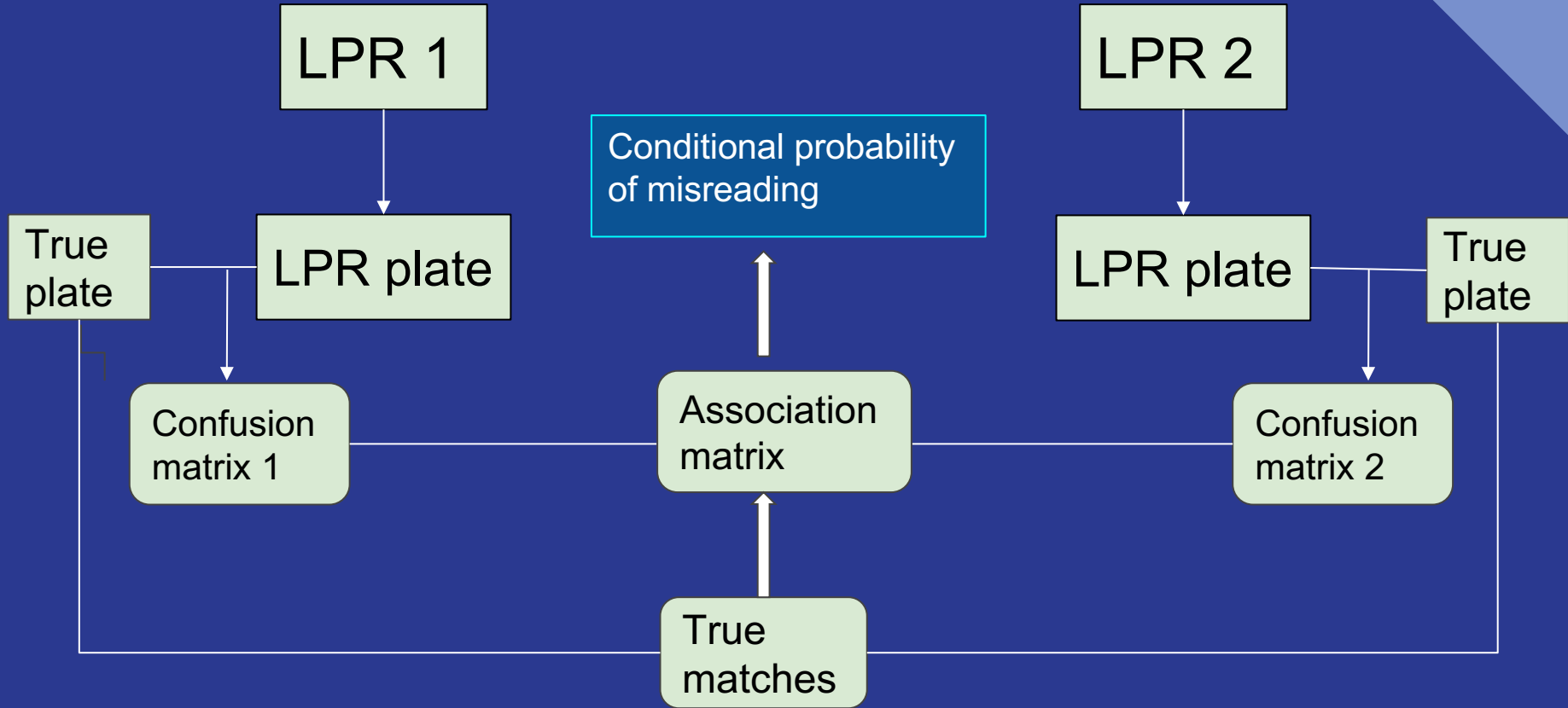
Goal: To judge whether
Different plate characters
are from the same car

Constraints

1. The travel time of LPR1 to LPR2
2. The ED of plate 1 change to plate 2
3. The conditional probabilities of character transition

Less ED, higher probability, in the time period

Association Matrix



Edit Distance Operation

$$d(x \rightarrow y) = \min\{d(i-1, j-1) + \gamma(x_i \rightarrow y_j), d(i-1, j) + \gamma(x_i \rightarrow \varepsilon), d(i, j-1) + \gamma(\varepsilon \rightarrow y_j)\}$$

Association Probability

$$p(y|x) = \frac{p(x, y)}{p(x)} = \frac{\sum_t p(x, y|t)p(t)}{\sum_{y,t} p(x, y|t)p(t)}$$

$$p(y|x) = \sum_t p(y|t)p(t|x)$$

Self-learning Matching

$C(M)$ represents calculate association matrix from a set of matches M

- 1) $k = k + 1$;
- 2) $M_k = M(C_{k-1})$;
- 3) $C_k = C(M_k)$;
- 4) Stop if $C_k - C_{k-1} < \varepsilon$.

Research Plan

1. Work on ED algorithm, self-learning algorithm of matching
2. Work on the matching part and weight function by python
3. Calibrate the parameters and validate them

Done

1. Read papers
2. Determine the project frame

Next step

Learn matlab and transform the matlab code into python code

Challenges

Challenges Already Faced:

- Sufficient Training Data
- Character Cutting Details
- Clearer Images
- Handling of Similar Characters

Foreseeable Challenges:

- Adapting Matlab Code
- Meshing Network and Matching



THANKS FOR LISTENING,
ANY QUESTIONS?