



*Modeling of a Graphene  
Membrane Rupture with DFTB  
and Improving its  
Computational Efficiency*

---

*By: Krystle Reiss, Jacob Blazejewski,  
Jacek Jakowski, Kwai Wong*

*CSURE Program 2015*

## Abstract

Density Functional Tight Binding (DFTB) is being used to find the cause of the catastrophic rupture of a graphene membrane under the effect of an electric field. Efforts are also being made to increase the computational efficiency of the program by replacing LAPACK calls with ScaLAPACK calls.

## Introduction

DFTB+ is being used to determine the cause of a graphene membrane rupture under the influence of an electric field.<sup>1</sup> When an electric field of 3 V/nm is applied to a graphene membrane suspended in a 1 M KCl solution, the membrane ruptures catastrophically, sometimes ripping completely in half. Several different variations of graphene membranes are being tested under varying conditions using molecular dynamics (MD) simulations.

Unfortunately running these DFTB calculations is extremely computationally expensive, with the most demanding calculations being linear algebra operations. The time spent on these operations is divided amongst evaluating forces, determining electronic structure and moving and handling the matrices to be used in the operations.

Carbons	Hydrogens	Corners	Flat or Warped	
218	40	Free	Flat	
			Warped	
	58	Frozen	Flat	
			Warped	
	508	62	Free	Flat
				Warped
90		Frozen	Flat	
			Warped	

**Table 1** gives all types of membranes used in MD simulations

The DFTB code utilizes Linear Algebra Package (LAPACK) functions to perform these calculations. Under these routines DFTB calculations of certain systems can still take far too long to be practical. In an attempt to speed up the software's calculations the LAPACK routines are therefore being replaced with Scalable LAPACK (ScaLAPACK) routines.

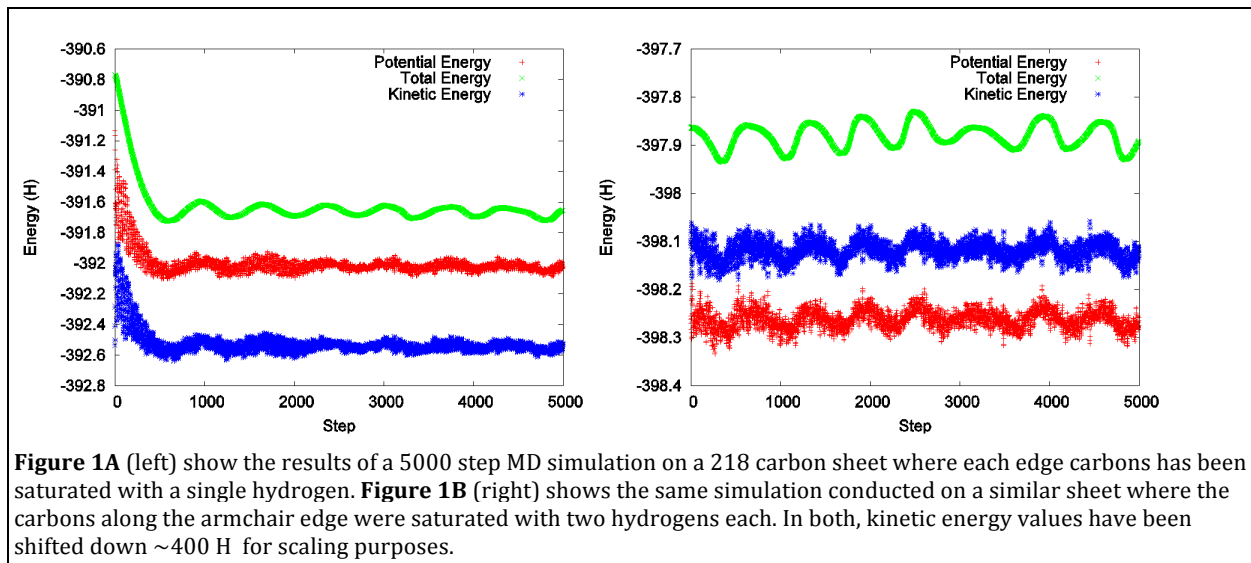
## Modeling of Graphene

Graphene, the two-dimensional form of graphite, is a fairly new material with many fascinating properties. Stronger than its equivalent weight in steel and very elastic, graphene is composed of a highly conjugated system of carbon atoms giving it 150 times the mobility of silicon. This means that graphene is an extremely good conductor. However, graphene is not yet a viable replacement for silicon switches in electronic devices, as graphene has no band gap. Silicon is a semiconductor, meaning that its band gap is just small enough for electrons to cross it if an electric field of suitable magnitude is applied. When no electric field is applied, silicon's electrons are unable to cross the gap. Graphene's lack of a band gap makes it metallic and electrons can move between HOMO and LUMO energy levels without the application of an electric field. Since graphene cannot be activated and deactivated like silicon can, it cannot generate binary code, which inhibits its ability to replace silicon in electronics.

Dr. Ivan Vlassiuk has been experimenting with applying electric fields to circular graphene membranes suspended in a 1 M potassium chloride aqueous solution. When an electric field with a strength of 3 V/nm is applied to these membranes, they rupture. There is no correlation between membrane size and rupture. The tear is so catastrophic, sometimes ripping the membrane entirely in half, that its cause cannot be determined. It is

possible that there are defects in the membrane, such as a Stone-Wales defect or a vacancy site,<sup>2</sup> or it may be that an ion is forced through the membrane, causing the rupture.

Computational methods, specifically DFTB+, are being used to determine why the membrane is rupturing. Because of its efficiency, DFTB is ideal for this type of simulation. Molecular dynamics (MD) simulations were set to run for femtosecond 5000 timesteps but were limited to 24-hour runtimes due to scheduling protocols. MD simulations were run using the VelocityVerlet driver with the NoseHoover thermostat set to 300 K and the coupling strength was 600 cm<sup>-1</sup>. The Hamiltonian was DFTB with an SCC tolerance of 1.0•10<sup>-6</sup>. The Fermi filling temperature was originally set to 0 K, but the SCC failed to converge at this temperature. When increased to 300 K, convergence was achieved, so this temperature was used throughout the rest of the simulations. Figure 1A and 1B show the results of these basic MD simulations.

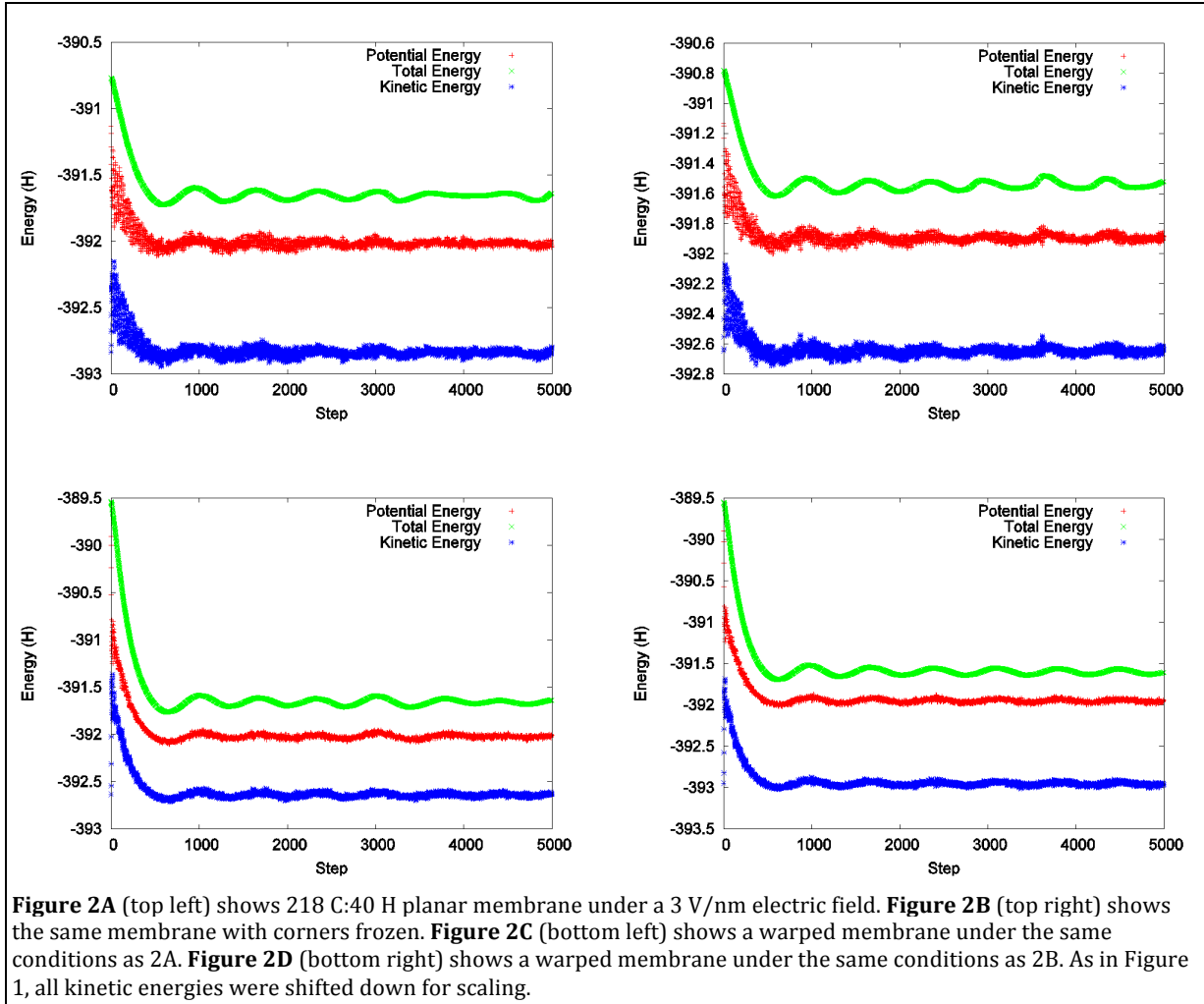


Unfortunately, larger sheet (508 and 1018 carbons) take much more time and do not finish the 5000 step MD simulation within the 24-hour wall clock limit. The 508-carbon membrane is able to complete 1500 to 2500 steps, depending on edge saturation, while the

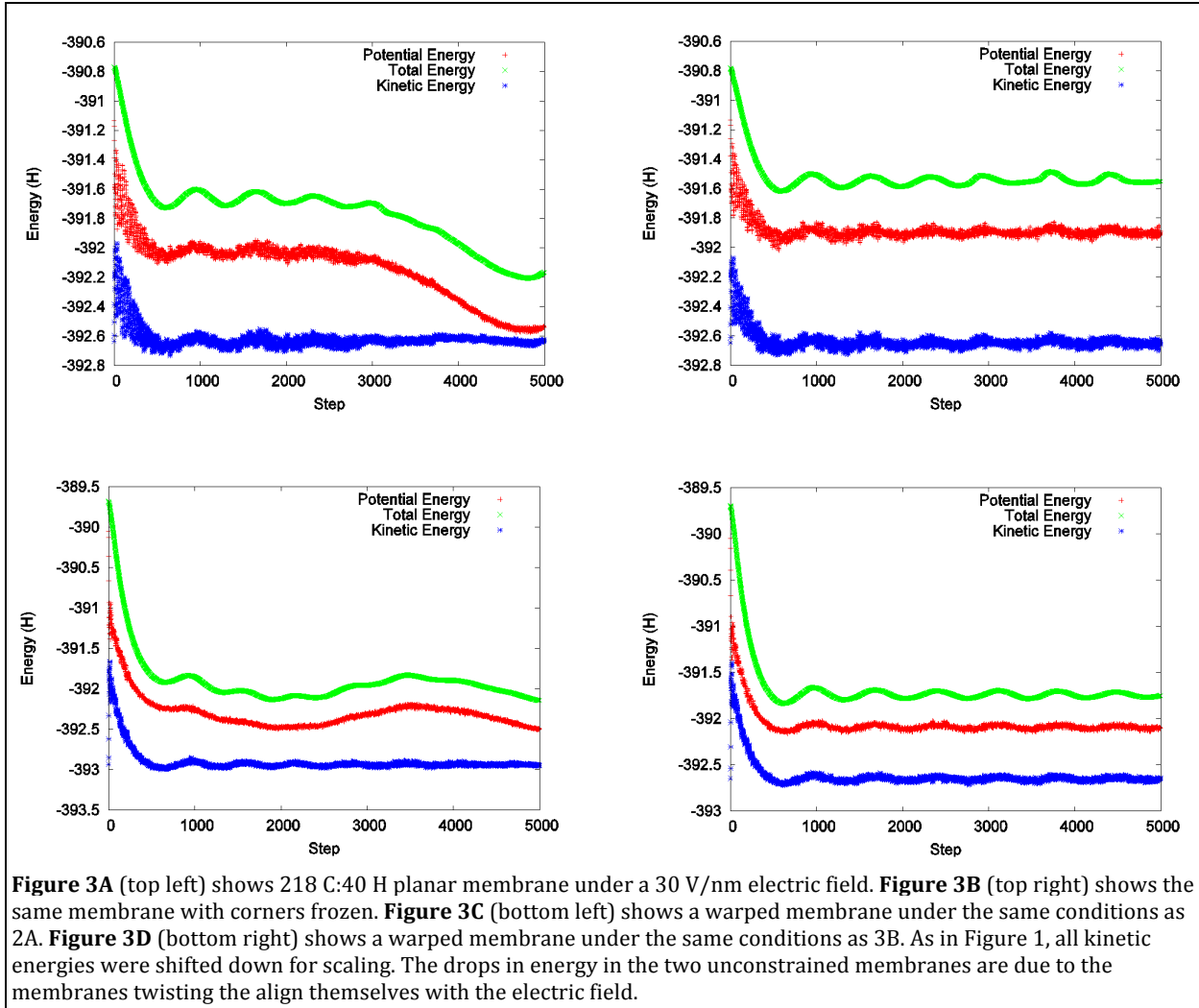
1006-carbon membrane does not even finish 300 steps. Even utilizing the GPU, the 1006-carbon membrane only increased its completed steps by ~50%. This led to the largest membrane being dropped from simulations, even though it would have provided the most realistic results. The 508-carbon membranes completed enough steps for the results to be considered meaningful. The smallest membrane, 218 carbons, finished the MD simulation within twelve hours.

In addition to differently sized membranes, the effects of constraints and waves were also evaluated. Two types of constraints were tested: freezing all membrane edges and freezing only the corners. Freezing entire edges was deemed to be too limiting as it prevented the natural dynamics of the system and so was abandoned. Frozen corners allowed for adequate membrane movement and membranes constrained in this way were tested alongside unconstrained membranes. To create waves in the membranes, an MD simulation was run applying a temperature of 2000 K to the system. This caused the membrane to spasm and warp, creating the desired waves. This allowed for points of polarity to form when an electric field was applied. It should be noted that unless constrained, the membranes reassumed their planar forms upon the removal of the extreme temperature.

To simulate the application of a 3 V/nm electric field, two point charges ( $\pm 15$  eV) were placed on either side of the membrane 10.00 nm away along the y axis (normal to the membrane). No significant effects were noted except a minor flattened region in the unconstrained planar membrane (Figure 2A). Initial drops in energy show the membranes moving into their ideal geometries. The warped membrane (2C & 2D) have larger initial energy drops as they attempt to reassume their planar shapes.

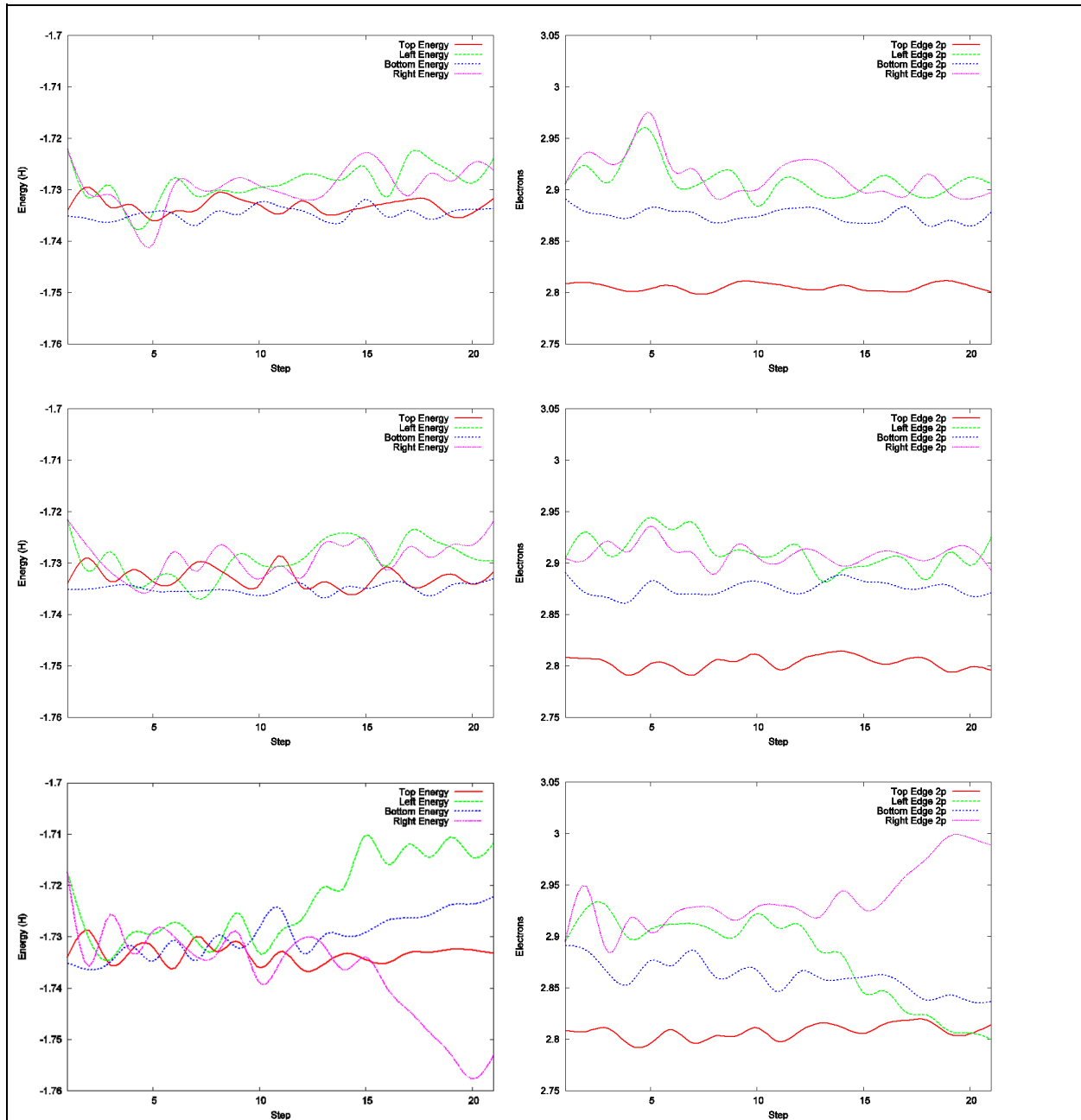


With no significant effects caused by the 3 V/nm field, the field strength was increased to 30 V/nm by increasing both of the point charges tenfold. Although it did not break any of the membranes, this did cause significant movement in the unconstrained membranes. These twisted to align themselves with the field, shown by the second major drop in energy in Figure 3A & 3C.



To more closely examine what phenomena might be occurring during the simulation, single point calculations were performed for 21 individual steps from the overall MD simulation (every 250th step from 0 to 5000). From these steps, data from a carbon atom on each edge (C10, C55, C109, C164) was taken, including orbital populations and resolved total energy. Samples of these results are given in Figure 4. There were no significant effects caused by the 3 V/nm electric field. Movement caused by the 30 V/nm field is clearly evident in the single point calculations as the left edge moved toward the anode and right edge toward the cathode. This caused a spike in the electron population of

the 2p orbitals on the right edge and a drop on the left edge. Conversely the resolved total energy dropped near the cathode and increased near the anode.

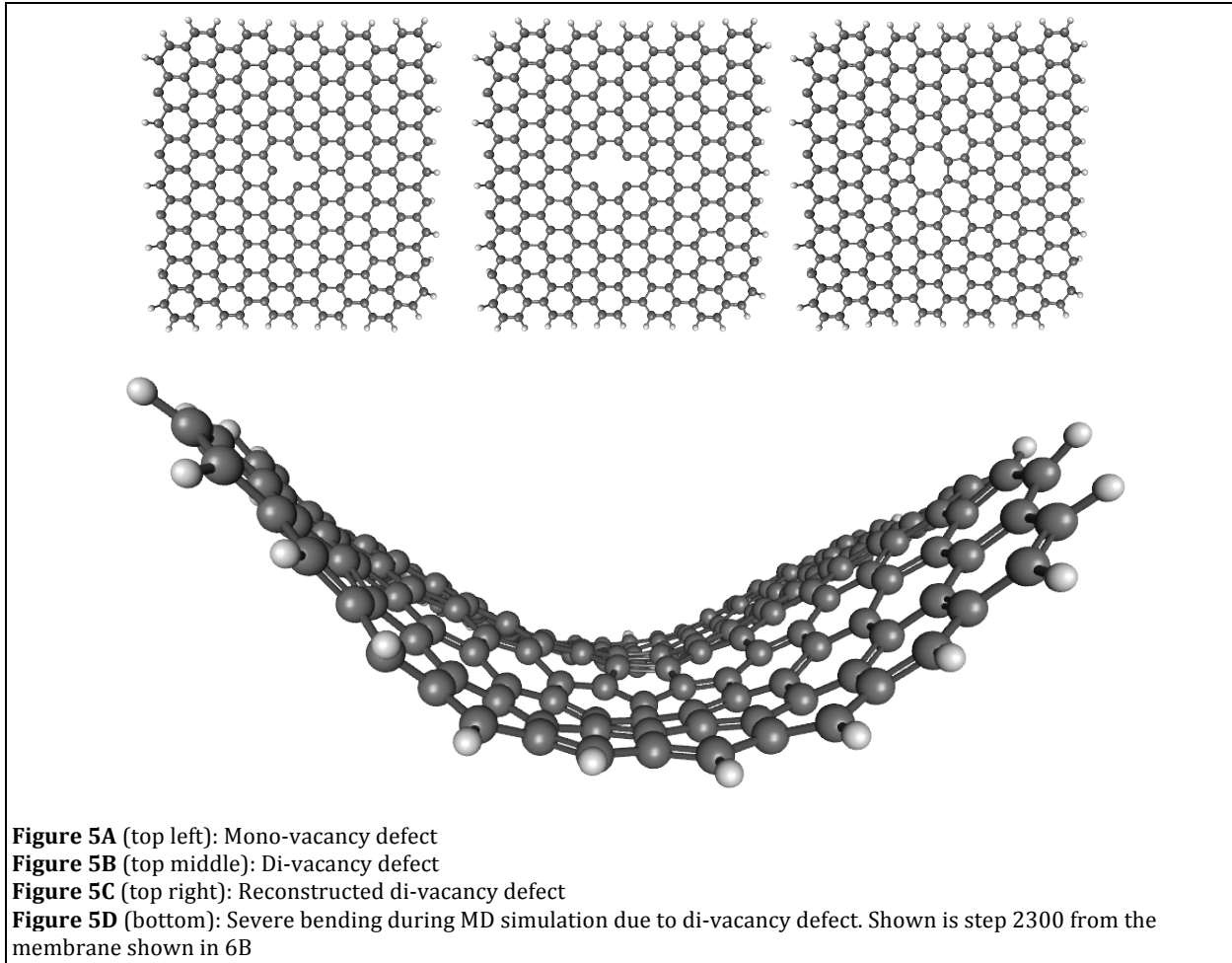


**Figure 4A** (top left) is the energy of a 218 C:40 H membrane. **Figure 4B** (top right) is the filling of 2p orbitals for the same membrane. The top edge carbon is lower in energy as it is bonded to three other carbons, whereas as the others are bound to two carbons and a single hydrogen. **Figure 4C** (middle left) is the energy of the same membrane under a 3 V/nm electric field. **Figure 4D** (middle right) is the filling of 2p orbitals for the same membrane under a 3 V/nm electric field. **Figure 4E** (bottom left) is the energy of the same membrane under a 30 V/nm electric field. The drastic split between the left and right edges was caused by the membrane aligning itself with the field. **Figure 4F** (bottom right) is the filling of 2p orbitals of the same membrane under a 30 V/nm electric field.



As graphene's mobility is so high, it is unlikely that the membrane rupture is due to an electric field alone. This is supported by the results shown in Figure 4. As even the 30 V/nm field applied in a vacuum did not significantly stress the membrane, it is more likely that the rupture was due to imperfections in the membrane or an ion puncturing it. There are several types of imperfections common to graphene membranes. The first, and most simple, are vacancy-type defects. In these, one or more carbons are absent from the graphene membrane, disturbing the conjugated system and lowering the strength of the membrane. Six variations of a vacancy-type defect were created for these simulations. These can be seen in Figure 5. While initial MD simulations showed no apparent difference between a mono-vacancy and a pristine graphene membrane, the di-vacancy defects allowed for significantly more warping movement in the membrane, comparable to that seen in a pristine membrane subjected to 2000 K temperatures. After initial MD simulations were run to acquire baseline results, a 3 V/nm field was applied to each of the membranes in addition to warped versions of the double vacancy defects output from the original MD simulations. Simulations were run both with and without frozen corners.

So far these simulations with defective sheets have not yielded a rupture. Future simulations will attempt to force an ion, such as fluoride, through the membrane. As the membrane was suspended in an ionic solution when it ruptured, it is possible that the rupture was caused by an ion being shot through the membrane by the electric field. Fluoride will be an ideal candidate for DFTB MD simulations as it is extremely electronegative (meaning it will not lose its electron easily and become neutral) and it is small with fewer non-valence electrons for DFTB to estimate for. This anion will be placed between the membrane and the anode in the hopes that it may puncture the membrane.



## Improving Computational Speed of DFTB

Even though DFTB is a semi-empirical method, which allows it to be faster than more traditional methods such as Density Functional Theory (DFT), the code can be computationally expensive when evaluating large systems. The largest cost comes from the linear algebra operations, such as matrix-matrix multiplication, Cholesky factorization, and diagonalization. Current DFTB code utilizes LAPACK (Linear Algebra Package) functions to perform these basic operations. LAPACK is inherently a serial code. There are some libraries that allow LAPACK to use multiple threads to perform calculations faster. However, when executing calculations on a supercomputer it is best to use

functions that can operate over multiple nodes that are working in parallel. ScaLAPACK was developed for just such a purpose. ScaLAPACK calls are designed utilize a distributed memory system that is then run in parallel. The distributed memory allows a global input matrix to be split into smaller pieces. These smaller pieces are then each sent to their own processor, where the desired linear algebra function is performed. Each processor receiving a portion of the matrix operates in parallel, allowing for faster calculations.

ScaLAPACK functions are able to communicate between various compute nodes by utilizing Basic Linear Algebra Communication Subprograms (BLACS). BLACS is easily initiated with four function calls. A call to `blacs_pinfo3` sets up the virtual machine that will be using the process grid to operate in parallel. It determines the number of processes available for use in the process grid as well as labels each process for the user to have a better way of distinguishing the processes. The `blacs_get3` call establishes a context label for the process grid that is then used to identify this function throughout the rest of the code. This label is especially important when more than one process grid is being operated within one code. Next, the `blacs_gridinit3` function takes every available CPU process and assigns it coordinates in the machines process grid. The user is able to selectively shape the desired process grid size by inputting the desired dimensions of the. In all work for this project only square process grids were used for ease of visualization and computation. Lastly, a call to `blacs_gridinfo3` simply returns information about the process grid with the input context label argument. In other words it serves as a double check that all process grid information was correctly established. Once a process grid is finished being used it should be released using `blacs_gridexit3` to allow the context label to be recycled if necessary. The

`blacs_exit3` call releases all memory allocated for the process grid as well as any remaining process grid labels.

```

...
|=====INITIALIZE PROCESS GRID=====|
prow = 2 ! number of process rows
pcol = 2 ! number of process columns
mb   = 6 ! number of columns in block
nb   = 6 ! number of rows in block

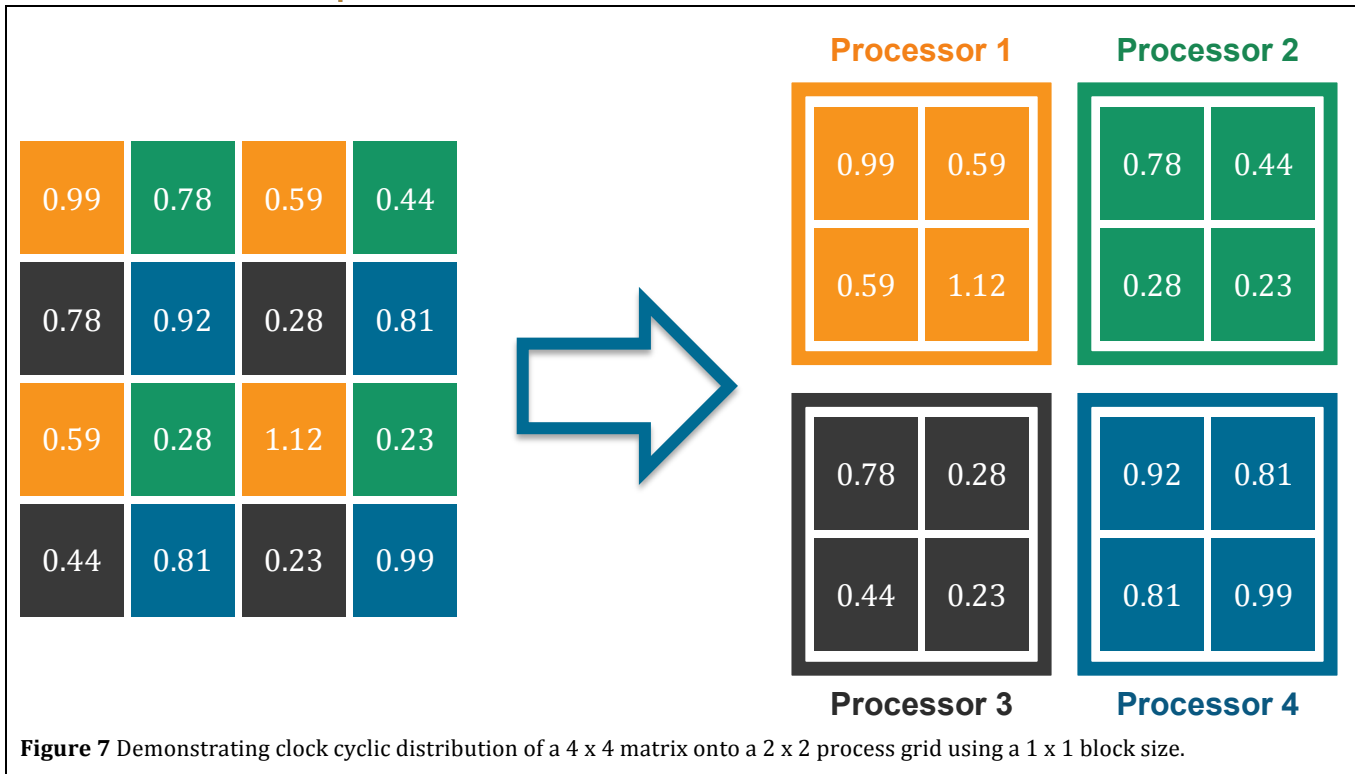
call blacs_pinfo (me,procs)
call blacs_get   (0, 0, icontxt)
call blacs_gridinit(icontxt, 'R', prow, pcol)
call blacs_gridinfo(icontxt, prow, pcol, myrow, mycol)
...

|=====END BLACS=====|
call blacs_gridexit(icontxt)
call blacs_exit(0)
...

```

**Figure 6A** (top) shows ample calls for initializing BLACS process grid, while **Figure 6B** (bottom) shows sample calls for terminating a BLACS process grid (bottom)

After the process grid has been created the global matrix must be divided over the process grid. Each CPU process on the grid receives a local array, which is a portion of the global matrix. The data is distributed in a block-cyclic fashion<sup>4</sup> (see Figure 7). The local arrays utilize dynamic memory allocation. This means each process must allocate memory space for the local array, and deallocate the memory after the local arrays are no longer needed. To perform the block cyclic distribution, two subroutines were found to accomplish this task<sup>5</sup> (see Appendix I). One takes the coordinates of an entry in the global matrix and then returns the entry's CPU process grid's coordinate as well as its local array coordinate. The other works in the opposite direction by using the coordinates of a local array entry along with its process grid location to obtain its global array coordinates (see Appendix II).



Each ScaLAPACK call requires an array descriptor to trace every global memory entry to its process and process array location.

```

****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK****
ides_a(1) = 1           ! descriptor type
ides_a(2) = icontxt    ! blacs context
ides_a(3) = n           ! global number of rows
ides_a(4) = n           ! global number of columns
ides_a(5) = nb         ! row block size
ides_a(6) = nb         ! column block size
ides_a(7) = 0          ! initial process row
ides_a(8) = 0          ! initial process column
ides_a(9) = myArows    ! leading dimension of local array

```

**Figure 8** Sample array descriptor

Once the matrix has been distributed and an array descriptor successfully assigned the user is ready to call a ScaLAPACK function. Functions that were of specific interest to this investigation are seen in Table 2.<sup>3</sup>

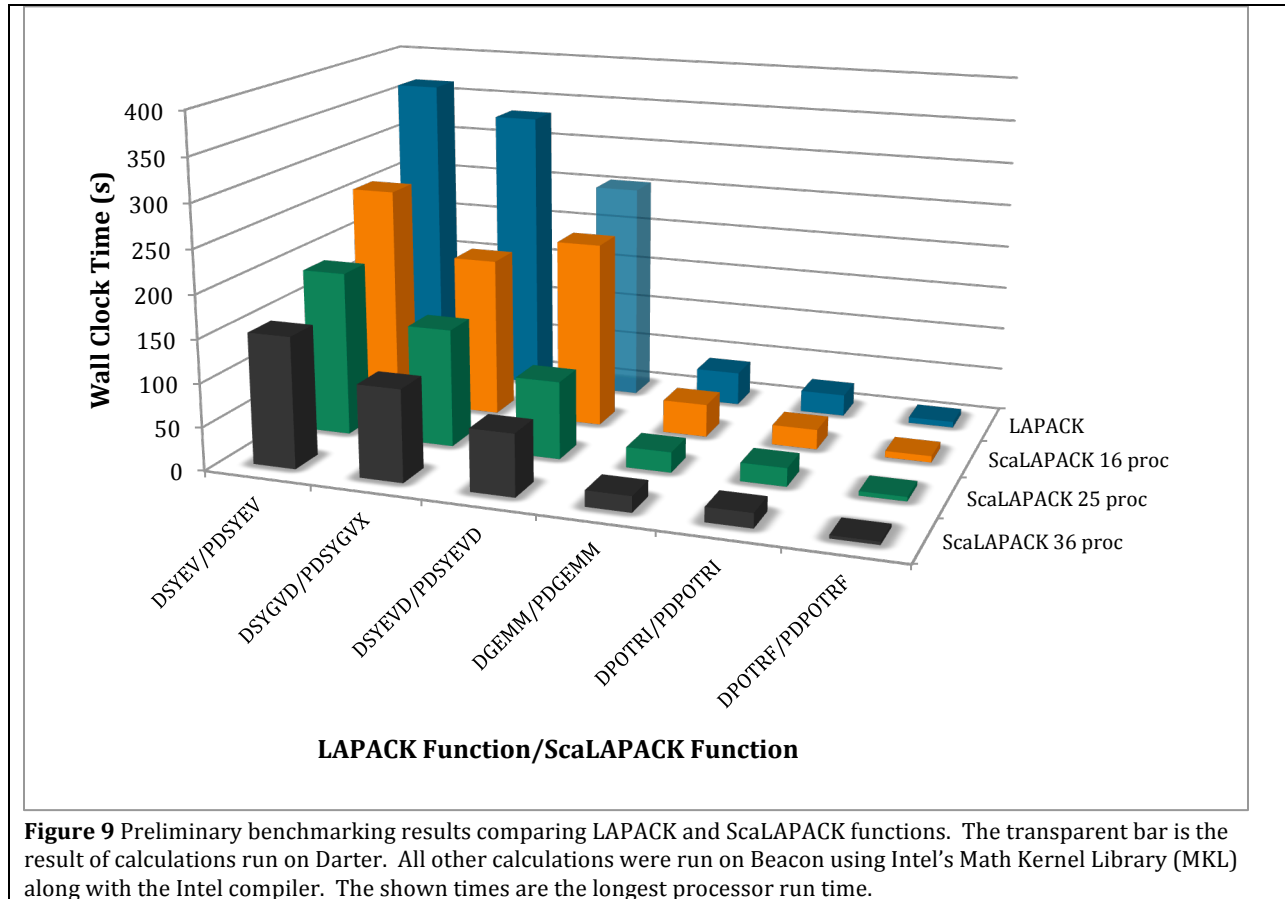
LAPACK Function	ScaLAPACK Function	Function
DGEMM	PDGEMM	Performs $\alpha AB = \beta C$ , where $\alpha$ and $\beta$ are scalars and A,B,C are all N x N matrices
DPOTRF	PDPOTRF	Performs a Cholesky factorization of a real symmetric positive definite N x N matrix utilizing solely its upper or lower triangular matrix
DPOTRI	PDPOTRI	Inverts a real symmetric positive definite N x N matrix by utilizing the output from DPOTRF/PDPOTRF
DSYEV	PDSYEV	Determines the eigenvalues, and if desired, eigenvectors of an N x N real symmetric matrix.
DSYEVD	PDSYEVD	Determines the eigenvalues, and if desired, eigenvectors of an N x N real symmetric matrix utilizing a divide and conquer algorithm
DSYGVD	PDSYEVD	Determines the eigenvalues, and if desired, eigenvectors of the following eigenproblem $A*x = \lambda B*x$ , where A and B are symmetric positive definite N x N matrices.

**Table 2:** LAPACK functions and their ScaLAPACK equivalents that were used in the benchmarking. See appendices for examples of code.

Common parameters required of a ScaLAPACK function include the name of the local array along with its array descriptor, and the coordinates of its leading entry. Some functions allow for extra calculation options such as utilizing the transpose of an input matrix or solving different arrangements of eigenvector problems. Eigen solver functions also require work matrices to allow for adequate memory space to perform calculations.

Rather than simply replacing LAPACK calls in the DFTB code with ScaLAPACK calls, a little bit of benchmarking was done. All of the ScaLAPACK codes from Table 2 were combined into one code and timed (see the Appendix II for benchmarking code). The following graph demonstrates preliminary speed up seen when using ScaLAPACK

functions. As the process grid size of ScaLAPACK is increased, so did the speed of each calculation.



All modifications to the DFTB code have taken place mainly in the `scf_diis_atrs` subroutine in the `scf.f90` file. The BLACS process grid initiation and termination have been added to the `prog.f90` file. LAPACK functions are being replaced with ScaLAPACK functions by inserting subroutines that contain the ScaLAPACK function call in place of LAPACK functions (See Appendix III for subroutines). The modified DFTB code is then tested by running a single point MD simulation of an ethene molecule and comparing its results with those of LAPACK DFTB. No benchmarking has been performed on the modified DFTB code as of yet. Currently, only the LAPACK matrix-matrix multiplication function (DGEMM) has been successfully replaced with the ScaLAPACK matrix-matrix



multiplication (PDGEMM). Work is also being done to replace the LAPACK eigensolver (DSYEV) with the ScaLAPACK eigensolver (PDSYEV). Unfortunately there is an error in ScaLAPACK's eigenvectors, which is skewing the DFTB calculations. More work is still needed to determine the exact cause of the problem.

The next steps of this project will include continuing to push the limits of ScaLAPACK routines to determine the ideal parameters for process grids. Items to be explored are adjusting the block size to be larger, distributing contiguous blocks of memory, and continuing to increase process grid size. The ultimate goal is to be able to perform 1 MD timestep in under a minute for large systems. As for the DFTB code, once the eigen solver is fixed, the rest of the investigated ScaLAPACK routines will also be added to the code as subroutines. There will also be some investigation on improving the memory efficiency of the DFTB code by having it generate the global matrix data within the local process arrays.



## Acknowledgements

We would like to thank the National Science Foundation for funding our research this summer along with University of Tennessee, Knoxville and Oak Ridge National Lab for hosting the CSURE program.

## References

- [1] DFTB+[Computer software].(2013).Retrieved from <http://www.dftb-plus.info>
- [2] Daniels, C.; Horning, A.; Phillips, A.; Massote, D.; Liang, L.; Bullard, Z.; Sumpter, B.; Meunier, V. Mechanisms Of Stress Release in Graphene Materials.
- [3] *NETLIB Repository*. University of Tennessee-Knoxville & Oak Ridge National Lab. Web. 7
- [4] LibSci Example <https://www.nersc.gov/users/software/programming-libraries/math-libraries/libsci/libsci-example/> (accessed Jun 2015).
- [5] Susan , B. Details of Example Program #1  
<http://netlib.org/scalapack/slug/node28.html> (accessed Jul 2015).

## Appendix I : Block-Cyclic Distribution Code

! convert global index to local index in block-cyclic distribution

```
subroutine g2l(i,n,np,nb,p,il)

implicit none
integer :: i      ! global array index, input
integer :: n      ! global array dimension, input
integer :: np     ! processor array dimension, input
integer :: nb     ! block size, input
integer :: p      ! processor array index, output
integer :: il     ! local array index, output
integer :: im1

im1 = i-1
p   = mod((im1/nb),np)
il  = (im1/(np*nb))*nb + mod(im1,nb) + 1

return
end
```

! convert local index to global index in block-cyclic distribution

```
subroutine l2g(il,p,n,np,nb,i)

implicit none
integer :: il     ! local array index, input
integer :: p      ! processor array index, input
integer :: n      ! global array dimension, input
integer :: np     ! processor array dimension, input
integer :: nb     ! block size, input
integer :: i      ! global array index, output
integer :: ilm1

ilm1 = il-1
i    = (((ilm1/nb) * np) + p)*nb + mod(ilm1,nb) + 1

return
end
```

## APPENDIX II : ScaLAPACK Benchmarking Code

```

!+++++
!+++++
! Timing of the ScaLAPACK: PDGEMM,PDPOTRI,PDPOTRF,PDSYEV,PDSYEV,D,PDSYGVX
! filename:  time_scalapack.f90
! compile:  mpiifort -o timing.f90 test_scalapack.f90
!+++++
! input:    input.txt
!          prow   number of rows in proc grid
!          pcol   number of columns in proc grid
!          n      number of rows/columns in matrix A
!          nb     matrix distribution block size

! ooutput:  fort.u, where u=10+processor number, and stdout
!+++++
!+++++

use timing
implicit none

integer :: MC, MM, TRF, TRI, EV, EVD, GVX !if loop variables 1 = run
integer :: prin ! matrix print variable
integer :: n, nb ! problem size and block size
integer :: m, nz ! number of eigen values and vectors
integer :: myunit ! local output unit number
integer :: myArows, myAcols ! size of local subset of global array
integer :: i,j, igrd,jgrid, iproc,jproc, myi,myj, pi ! navigating variables
integer open_status, close_status ! variables for read in files
integer :: numroc ! blacs routine
integer :: me, procs, icontxt, prow, pcol, myrow, mycol ! blacs data
integer :: lwork, liwork !eigen variables
integer :: info ! scalapack return value
integer, dimension(:), allocatable :: ifail,iclustr !PDSYGVX outputs
integer, dimension(:), allocatable :: iwork ! work array
integer, dimension(9) :: ides_a, ides_b, ides_c, ides_z ! scalapack array desc
real*8, dimension(:), allocatable :: W,WW, work ! eigen values and work arrays
real*8, dimension(:), allocatable :: gap ! PDSYGVX output
real*8, dimension(:,,:), allocatable :: A,B,C,D,E,F,Z,ID ! global arrays
real*8, dimension(:,,:), allocatable :: myA,myB,myC,myZ ! local arrays
real*8 :: vl, vu, il, iu,x,y !unreferenced range values
real*8 :: abstol,orfac,PDLAMCH ! PDSYGVX variables

! Read problem description

! open(unit=15,file="./ABCp.txt",status="old",iostat=open_status)
! read(15,*)prow
! read(15,*)pcol
! read(15,*)n
! read(15,*)nb

!=====VARIABLE READ IN=====
open(unit=15,file='./input.txt',status='old',iostat=open_status)
read(15,*),prow ! number of process rows
read(15,*),pcol ! number of process columns
read(15,*)n ! leading dimension of global matrix
read(15,*)nb ! leading dimension of block size

read(15,*),prin ! if prin=1 print all calculations
read(15,*)MC ! if 1 print global matrices
read(15,*)MM ! if 1 perform PDGEMM on A*B = C
read(15,*)TRF ! if 1 perform PDPOTRF Cholesky factorization of A
read(15,*)TRI ! if 1 perform PDPOTRI of A (MUST HAVE TRF.eq.1)

```

```

        read(15,*),EV      ! if 1 perform PDSYEV to compute eigenvalues and optionally
eigenvectors
        read(15,*),EVD    ! if 1 perform PDSYEVD to compute eigenvalues and optionally
eigenvectors
        read(15,*),GVX    ! if 1 perform PDSYGVX to compute eigenvalues and optionally
eigenvectors
        lwork = -1        ! must be -1 to give proper dimension for work
        liwork = (7 * N) + (8 * pcol) + 2 !must be -1 to give proper dimension for
liwork
        if (((n/nb) < prow) .or. ((n/nb) < pcol)) then
            print *,"Problem size too small for processor set!"
            stop 100
        endif
!=====GLOBAL MATRIX SET UP=====
        call time_start(1)

!****ALLOCATING GLOBAL MATRICES****
!MATRIX GUIDE:
! A  ::  PDGEMM, PDPOTRF, PDPOTRI
! B  ::  PDGEMM, PDSYEV
! C  ::  PDSYEVD
! D  ::  PDSYGVX
! E  ::  PDSYGVX
        allocate (A(N,N))
        allocate (B(N,N))
        allocate (ID(N,N)) ! will be the identity

! fill A and B with random numbers
        call random_number(A)
        call random_number(B)

        DO i = 1,N
            DO j = 1,N
                A(j,i)=A(i,j) ! assure A is symmetric
                B(j,i)=B(i,j) ! assure B is symmetric
                ID(i,j)=0.0d0
                ID(i,i)=1.0d0
            END DO
        END DO

! make A & B diagonal dominate to ensure positive definite
        A = A + (ID * N)
        B = B + (ID * N)

! the order of allocation is an attempt to maximize memory usage
        deallocate(ID)
        allocate (C(N,N))
        allocate (D(N,N))
        allocate (E(N,N))
        C = B
        D = A
        E = B
        call time_stop(1)
!=====INITIALIZE PROCESS GRID=====
        call blacs_pinfo (me,procs)
        call blacs_get (0, 0, icontxt)
        call blacs_gridinit(icontxt, 'R', prow, pcol)
        call blacs_gridinfo(icontxt, prow, pcol, myrow, mycol)
        myunit = 10+me !processor output file label "fort.myunit"
! process grid info check
        write(myunit,*)"-----"
        write(myunit,*)"Output for processor ",me," to unit ",myunit
        write(myunit,*)"Proc ",me,": myrow, mycol in p-array is ", &
            myrow, mycol
        flush(myunit)
! determining dimension of local array

```

```

myArows = numroc(n, nb, myrow, 0, prow)
myAcols = numroc(n, nb, mycol, 0, pcol)
! process grid info check
write(myunit,*)"Size of global array is ",n," x ",n
write(myunit,*)"Size of block is      ",nb," x ",nb
write(myunit,*)"Size of local array is ",myArows," x ",myAcols
flush(myunit)
! this prints the info check in the master output file
if (me.eq.0) then
write(*,*)"Size of global array is ",n," x ",n
write(*,*)"Size of block is      ",nb," x ",nb
write(*,*)"Size of local array is ",myArows," x ",myAcols
end if
!=====GLOBAL MATRIX PRINT CHECK=====
if (MC.eq.1) then
write(myunit,*)"--- matrix check ----"
write(myunit,*) 'Matrix A'
do i = 1,N
write (myunit,9998) (A(i,j), j=1,N)
end do
write(myunit,*)
write(myunit,*)
write(myunit,*) 'Matrix B'
do i = 1,N
write(myunit,9998) (B(i,j), j=1,N)
end do
write(myunit,*)
write(myunit,*) 'Matrix C'
do i = 1,N
write(myunit,9998) (C(i,j), j=1,N)
end do
write(myunit,*)
write(myunit,*) 'Matrix D'
do i = 1,N
write(myunit,9998) (D(i,j), j=1,N)
end do
write(myunit,*)
write(myunit,*) 'Matrix E'
do i = 1,N
write(myunit,9998) (E(i,j), j=1,N)
end do
write(myunit,*)
write(myunit,*) 'Matrix Z'
do i = 1,N
write(myunit,9998) (Z(i,j), j=1,N)
end do
write(myunit,*)
! write(myunit,*) 'Matrix ID'
! do i = 1,N
! write(myunit,9998) (ID(i,j), j=1,N)
! end do
! write(myunit,*)
! write(myunit,*) 'Matrix W'
! do i = 1,N
! write(myunit,9998) W(i)
! end do
end if

!=====TIMING PRINTING=====
write(*,*) 'Time for Matrix Generation (sec)', timetab(1)
!=====START PDGEMM=====
if (MM.eq.1) then
write(myunit,*)"*****PDGEMM*****"
!****INITIALIZE LOCAL ARRAYS****

```

```

allocate(myA(myArows,myAcols))
allocate(myB(myArows,myAcols))
allocate(myC(myArows,myAcols))

write(myunit,*)"--- before MM -----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi) ! see subroutines
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        myA(myi,myj) = A(i,j)
        myB(myi,myj) = B(i,j)
        myC(myi,myj) = 0.0d0
!   check matrix filling
        if (prin.eq.1) then
          write(myunit,*)"A(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myA(myi,myj), &
            "on proc(",iproc,",",jproc,")"
          write(myunit,*)"B(",i,",",j,")", &
            " --> myB(",myi,",",myj,")=",myB(myi,myj), &
            "on proc(",iproc,",",jproc,")"
          write(myunit,*)"C(",i,",",j,")", &
            " --> myC(",myi,",",myj,")=",myC(myi,myj), &
            "on proc(",iproc,",",jproc,")"
        end if
      end if
    end do
  end if
end do
flush(myunit)

!****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK****
ides_a(1) = 1      ! descriptor type
ides_a(2) = icontxt ! blacs context
ides_a(3) = n      ! global number of rows
ides_a(4) = n      ! global number of columns
ides_a(5) = nb     ! row block size
ides_a(6) = nb     ! column block size
ides_a(7) = 0      ! initial process row
ides_a(8) = 0      ! initial process column
ides_a(9) = myArows ! leading dimension of local array
! assigning descriptors to all local matrices
do i=1,9
  ides_b(i) = ides_a(i)
  ides_c(i) = ides_a(i)
enddo

!****CALL PDGEMM****
call time_start(2)
call pdgemm('T','T',n,n,n,1.0d0, myA,1,1,ides_a, &
  myB,1,1,ides_b,0.d0, &
  myC,1,1,ides_c )
call time_stop(2)

! Print results
write(myunit,*)"--- after MM -----"

do i=1,n
  call g2l(i,n,prow,nb,iproc,myi)
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then

```

```

        if (prin.eq.1) then
            write(myunit,*)"A(",i,",",j,")", &
                " --> myA(",myi,",",myj,")=",myA(myi,myj), &
                "on proc(",iproc,",",jproc,")"
            write(myunit,*)"B(",i,",",j,")", &
                " --> myB(",myi,",",myj,")=",myB(myi,myj), &
                "on proc(",iproc,",",jproc,")"
            write(myunit,*)"C(",i,",",j,")", &
                " --> myC(",myi,",",myj,")=",myC(myi,myj), &
                "on proc(",iproc,",",jproc,")"
        end if
    end if
end do
end if
end do
flush(myunit)

!****DEALLOCATING LOCAL MATRICES****
deallocate(myA, myB, myC)
end if

!=====TIMING PRINTING=====
if (MM.eq.1) then
write(*,*) 'Time for PDGEMM (sec)', timetab(2)
end if

!=====END PDGEMM=====

!=====START PDPOTRF=====
if (TRF.eq.1) then
write(myunit,*)"*****PDPOTRF*****"
!****INITIALIZING LOCAL ARRAYS****
allocate(myA(myArows,myAcols))

write(myunit,*)"--- before Cholesky ----"
do i=1,n
    call g2l(i,n,prown,nb,iproc,myi) ! see subroutines
    if (myrow==iproc) then
        do j=1,n
            call g2l(j,n,pcol,nb,jproc,myj)
            if (mycol==jproc) then
                myA(myi,myj) = A(i,j)
! check matrix filling
                if (prin.eq.1)then
                    write(myunit,*)"A(",i,",",j,")", &
                        " --> myA(",myi,",",myj,")=",myA(myi,myj), &
                        "on proc(",iproc,",",jproc,")"
                end if
            end if
        end do
    end do
end if
flush(myunit)

!****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK
ides_a(1) = 1 ! descriptor type
ides_a(2) = icontxt ! blacs context
ides_a(3) = n ! global number of rows
ides_a(4) = n ! global number of columns
ides_a(5) = nb ! row block size
ides_a(6) = nb ! column block size
ides_a(7) = 0 ! initial process row
ides_a(8) = 0 ! initial process column
ides_a(9) = myArows ! leading dimension of local array
! assigning descriptors to all local matrices

```

```

do i=1,9
  ides_b(i) = ides_a(i)
  ides_c(i) = ides_a(i)
end do

!****CALL PDPOTRF****
call time_start(3)
call pdpotrf('U',n, myA,1,1,ides_a,info)
call time_stop(3)

! Print results
if (prin.eq.1) then
write(myunit,*)"--- after Cholesky -----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi)
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        write(myunit,*)"A(",i,",",j,")", &
          " --> myA(",myi,",",myj,")=",myA(myi,myj), &
          "on proc(",iproc,",",jproc,")"
      end if
    end do
  end if
end do
flush(myunit)
end if

!****DEALLOCATE LOCAL MATRICES****
deallocate(myA)

end if

!=====TIMING PRINTING=====
if (TRF.eq.1) then
write(*,*) 'Time for PDPOTRF (sec)', timetab(3)
end if

!=====END PDPOTRF=====

!=====START PDPOTRI=====
if (TRI.eq.1) then
write(myunit,*)"*****PDPOTRI*****"
!****INITIALIZE LOCAL ARRAYS****
allocate(myA(myArows,myAcols))
write(myunit,*)"--- before inversion -----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi) ! see subroutine
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        myA(myi,myj) = A(i,j)
! check matrix filling
        if (prin.eq.1) then
          write(myunit,*)"A(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myA(myi,myj), &
            "on proc(",iproc,",",jproc,")"
        end if
      end if
    end do
  end if
end do
flush(myunit)

```



```

!****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK****
  ides_a(1) = 1      ! descriptor type
  ides_a(2) = icontxt ! blacs context
  ides_a(3) = n      ! global number of rows
  ides_a(4) = n      ! global number of columns
  ides_a(5) = nb     ! row block size
  ides_a(6) = nb     ! column block size
  ides_a(7) = 0      ! initial process row
  ides_a(8) = 0      ! initial process column
  ides_a(9) = myArows ! leading dimension of local array
!   assigning descriptors to all local matrices
  do i=1,9
    ides_b(i) = ides_a(i)
    ides_c(i) = ides_a(i)
  end do

!****CALL PDPOTRI****
  call time_start(4)
  call pdpotri('U',n, myA,1,1,ides_a,info)
  call time_stop(4)

! Print results
  if (prin.eq.1)then
    write(myunit,*)"--- after inversion -----"
    do i=1,n
      call g2l(i,n,prow,nb,iproc,myi)
      if (myrow==iproc) then
        do j=1,n
          call g2l(j,n,pcol,nb,jproc,myj)
          if (mycol==jproc) then
            write(myunit,*)"A(",i,",",j,")", &
              " --> myA(",myi,",",myj,")=",myA(myi,myj), &
              "on proc(",iproc,",",jproc,")"
          end if
        end do
      end if
    end do
    flush(myunit)
  end if

!****DEALLOCATING LOCAL MATRICES****
  deallocate(myA)
  end if

!=====TIMING PRINTING=====
  if (TRI.eq.1) then
    write(*,*) 'Time for PDPOTRI (sec)', timetab(4)
  end if

!=====END PDPOTRI=====
!****DEALLOCATION TO SAVE MEMORY****
  deallocate(A)
!****INITIALIZING MORE GLOBAL ARRAYS****
  allocate (Z(N,N))
  allocate (W(N))
  DO i = 1,N
    W(i) = 0.0d0
    DO j = 1,N
      Z(i,j)=0.0d0
    END DO
  END DO

!=====START PDSYEV=====
  if (EV.eq.1) then
    write(myunit,*)"*****PDSYEV*****"
!****INITIALIZE LOCAL ARRAYS****
    allocate(myB(myArows,myAcols))

```

```

allocate(myZ(myArows,myAcols))
allocate(work(1))
write(myunit,*)"--- before operation -----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi)
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        myB(myi,myj) = B(i,j)
        myZ(myi,myj) = Z(i,j)
        if (prin.eq.1) then
          write(myunit,*)"B(",i,",",j,")", &
            " --> myB(",myi,",",myj,")=",myB(myi,myj), &
            "on proc(",iproc,",",jproc,")"
          write(myunit,*)"Z(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
            "on proc(",iproc,",",jproc,")"
        end if
      end if
    end do
  end if
end do
flush(myunit)

!****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK****
ides_a(1) = 1      ! descriptor type
ides_a(2) = icontxt ! blacs context
ides_a(3) = n      ! global number of rows
ides_a(4) = n      ! global number of columns
ides_a(5) = nb     ! row block size
ides_a(6) = nb     ! column block size
ides_a(7) = 0      ! initial process row
ides_a(8) = 0      ! initial process column
ides_a(9) = myArows ! leading dimension of local array
! Assigning descriptors to all local matrices
do i=1,9
  ides_b(i) = ides_a(i)
  ides_z(i) = ides_a(i)
end do
write(myunit,*) 'descriptor arrays assigned'
write(myunit,*) 'Made it to PDSYEV'
flush(myunit)
!****CALL PDSYEV****
call time_start(5)
! first call is to obtain dimension for work array
call pdsyev('V','U',n,myB,1,1,ides_b,w,myZ,1,1,ides_z,work,lwork,info)
lwork = work(1) ! assinging lwork to proper value
deallocate(work) ! resizing work to perform calculation
allocate(work(lwork))
flush(myunit)
! second call performs actual calculation
call pdsyev('V','U',n,myB,1,1,ides_b,w,myZ,1,1,ides_z,work,lwork,info)
call time_stop(5)
write(myunit,*) 'Completed PDSYEV'

! print results
if (prin.eq.1) then
  write(myunit,*)"--- after operation -----"
  do i=1,n
    call g2l(i,n,prow,nb,iproc,myi)
    if (myrow==iproc) then
      do j=1,n
        call g2l(j,n,pcol,nb,jproc,myj)

```

```

        if (mycol==jproc) then
            write(myunit,*) "B(",i,",",j,")", &
                " --> myB(",myi,",",myj,")=",myB(myi,myj), &
                "on proc(",iprocc,",",jprocc,")"
            write(myunit,*) "Z(",i,",",j,")", &
                " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
                "on proc(",iprocc,",",jprocc,")"
        end if
    end do
end if
end do
write(myunit,*)"--- eigen values -----"
write(myunit, 9998) w
flush(myunit)
end if
!****DEALLOCATING ARRAYS****
deallocate(myB, myZ)
deallocate(work)
end if
!=====TIMING PRINTING=====
if (EV.eq.1) then
write(*,*) 'Time for PDSYEV (sec)', timetab(5)
end if
!=====END PDSYEV=====
!****DEALLOCATION TO SAVE MEMORY****
deallocate(B)
lwork = -1 ! reassin to perform PDSYEVD
! Reset W and Z
do i = 1,n
W(i) = 0.0d0
do j = 1,n
Z(i,j) = 0.0d0
end do
end do
!=====START PDSYEVD=====
if (EVD.eq.1) then
write(myunit,*)"*****PDSYEVD*****"
!****INITIALIZING LOCAL ARRAYS****
allocate(myC(myArows,myAcols))
allocate(myZ(myArows,myAcols))
allocate(work(1))
allocate(iwork(1))
write(myunit,*)"--- before operation -----"
do i=1,n
call g2l(i,n,prow,nb,iprocc,myi)
if (myrow==iprocc) then
do j=1,n
call g2l(j,n,pcol,nb,jprocc,myj)
if (mycol==jprocc) then
myC(myi,myj) = C(i,j)
myZ(myi,myj) = Z(i,j)
if (prin.eq.1) then
! check matrix filling
write(myunit,*) "B(",i,",",j,")", &
" --> myB(",myi,",",myj,")=",myC(myi,myj), &
"on proc(",iprocc,",",jprocc,")"
write(myunit,*) "Z(",i,",",j,")", &
" --> myA(",myi,",",myj,")=",myZ(myi,myj), &
"on proc(",iprocc,",",jprocc,")"
end if
end if
end do
end if
end do
end do
end do

```

```

flush(myunit)

!****PREPARE ARRAY DESCRIPTORS FOR SCALAPACK****
  ides_a(1) = 1      ! descriptor type
  ides_a(2) = icontxt ! blacs context
  ides_a(3) = n      ! global number of rows
  ides_a(4) = n      ! global number of columns
  ides_a(5) = nb     ! row block size
  ides_a(6) = nb     ! column block size
  ides_a(7) = 0      ! initial process row
  ides_a(8) = 0      ! initial process column
  ides_a(9) = myArows ! leading dimension of local array
!   assigning descriptors to all local matrices
  do i=1,9
    ides_c(i) = ides_a(i)
    ides_z(i) = ides_a(i)
  enddo
  write(myunit,*) 'descriptor arrays assigned'

!****CALL PDSYEVD****
  write(myunit,*) 'Made it to PDSYEVD'
  flush(myunit)
  call time_start(6)
!   first call is to obtain dimension for work and iwork
  call pdsyevd('V','U',n,myC,1,1,ides_c,w,myZ,1,1,ides_z,&
    work,lwork,iwork,liwork,info)
  lwork = work(1)      ! assinging lwork to proper value
  deallocate(work,iwork) ! resizing work and iwork to perform calculation
  allocate(work(lwork))
  allocate(iwork(liwork))
  flush(myunit)
!   second call performs actual calculation
  call pdsyevd('V','U',n,myC,1,1,ides_c,w,myZ,1,1,ides_z, &
    work,lwork,iwork,liwork,info)
  call time_stop(6)
  write(myunit,*) 'Completed PDSYEVD'
!   print results
  if (prin.eq.1) then
    do i=1,n
      call g2l(i,n,prow,nb,iproc,myi)
      if (myrow==iproc) then
        do j=1,n
          call g2l(j,n,pcol,nb,jproc,myj)
          if (mycol==jproc) then
            write(myunit,*)"B(",i,",",j,")", &
              " --> myB(",myi,",",myj,")=",myC(myi,myj), &
              "on proc(",iproc,",",jproc,")"
            write(myunit,*)"Z(",i,",",j,")", &
              " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
              "on proc(",iproc,",",jproc,")"
          end if
        end do
      end do
    end if
    flush(myunit)
    write(myunit,*)"--- eigen values ----"
    write(myunit, 9998) w
  end if
!****DEALLOCATING MATRICES****
  deallocate(myC,myZ)
  deallocate(work,iwork)
end if

!=====TIMING PRINTING=====
if (EVD.eq.1) then

```

```

write(*,*) 'Time for PDSYEVD (sec)', timetab(6)
end if
!=====END PDSYEVD=====
!****DEALLOCATION TO SAVE MEMORY****
deallocate(C)
!****INIRIALIZINF MORE GLOBAL ARRAYS****
allocate (ifail(N))
allocate (iclustr(2*(prow*pcol)))
allocate (gap(prow*pcol))
lwork = -1 ! reassign to perform PDSYGX
liwork = -1 ! reassign to perform PDSYGX
! Reset W and Z
do i = 1,n
  W(i) = 0.0d0
  do j = 1,n
    Z(i,j) = 0.0d0
  end do
end do
!=====START PDSYGX=====
if (GVX.eq.1) then
write(myunit,*)"*****PDSYGX*****"
!****ALLOCATING LOCAL ARRAYS****
allocate(myA(myArows,myAcols))
allocate(myB(myArows,myAcols))
allocate(myZ(myArows,myAcols))
allocate(work(1))
allocate(iwork(1))

!****DISTRIBUTING GLOBAL MATRIX****=
write(myunit,*)"--- before operation ----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi)
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        myA(myi,myj) = D(i,j)
        myB(myi,myj) = E(i,j)
        myZ(myi,myj) = Z(i,j)
! matrix check
        if (prin.eq.1) then
          write(myunit,*)"A(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myA(myi,myj), &
            "on proc(",iproc,",",jproc,")"
          write(myunit,*)"B(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myB(myi,myj), &
            "on proc(",iproc,",",jproc,")"
          write(myunit,*)"Z(",i,",",j,")", &
            " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
            "on proc(",iproc,",",jproc,")"
        end if
      endif
    enddo
  endif
enddo

! Assinging the appropriate value accodring to documentation
abstol = PDLAMCH(icontxt,'U')
!****PREPARE ARRAY DESCRIPTORS FOR SCLAPACK****
ides_a(1) = 1 ! descriptor type
ides_a(2) = icontxt ! blacs context
ides_a(3) = n ! global number of rows
ides_a(4) = n ! global number of columns
ides_a(5) = nb ! row block size

```

```

ides_a(6) = nb          ! column block size
ides_a(7) = 0          ! initial process row
ides_a(8) = 0          ! initial process column
ides_a(9) = myArows    ! leading dimension of local array
! assigning descriptors to all local matrices
do i=1,9
    ides_b(i) = ides_a(i)
    ides_z(i) = ides_a(i)
enddo

! write(myunit,*) 'descriptor arrays assigned'
write(myunit,*)'Made it to PDSYGVX'
flush(myunit)

!****CALL PDSYGVX****
call time_start(7)
! first call to get proper work array dimensions
call PDSYGVX(1,'V','A','L',N,myA,1,1,&
    ides_a,myB,1,1,ides_b,vl,vu,il,iu,&
    abstol,m,nz,w,orfac,myZ,1,1,ides_z,&
    work,lwork,iwork,liwork,ifail,iclustr,&
    gap,info)
! reassign proper dimensions for work arrays
lwork = work(1)
liwork = iwork(1)
deallocate(work,iwork)
allocate(work(lwork))
allocate(iwork(liwork))
! second call performs actual calculation
call PDSYGVX(1,'V','A','L',n,myA,1,1,&
    ides_a,myB,1,1,ides_b,vl,vu,il,iu,&
    abstol,m,nz,w,orfac,myZ,1,1,ides_z,&
    work,lwork,iwork,liwork,ifail,iclustr,&
    gap,info)
call time_stop(7)
write(myunit,*)'Completed PDSYGVX'

! Print Results
if (prin.eq.1) then
write(myunit,*)"---- after operation ----"
do i=1,n
    call g2l(i,n,prow,nb,iproc,myi)
    if (myrow==iproc) then
        do j=1,i
            call g2l(j,n,pcol,nb,jproc,myj)
            if (mycol==jproc) then
                write(myunit,*)"A(",i,",",j,")", &
                    "--> myA(",myi,",",myj,")=",myA(myi,myj), &
                    "on proc(",iproc,",",jproc,")"
                write(myunit,*)"B(",i,",",j,")", &
                    "--> myB(",myi,",",myj,")=",myB(myi,myj), &
                    "on proc(",iproc,",",jproc,")"
                write(myunit,*)"Z(",i,",",j,")", &
                    "--> myZ(",myi,",",myj,")=",myZ(myi,myj), &
                    "on proc(",iproc,",",jproc,")"
            end if
        end do
    end if
end do
flush(myunit)
write(myunit,*)"Number of eign values found:", m
write(myunit,*)"--- eigen values ----"
write(myunit, 9998) w
write(myunit,*)"# eigen vectors computed:", nz

```

```

end if
!***DEALLOCATING ARRAYS***
deallocate(myA,myB,myZ)
deallocate(work,iwork)
deallocate(ifaill,iclustr,gap)
end if
!=====TIMING PRINTING=====
if (GVX.eq.1) then
write(*,*) 'Time for PDSYGVX (sec)', timetab(7)
end if
!=====END PDSYGVX=====

!=====DEALLOCATE REMAINING MATRICES=====
deallocate(D,E,Z,W)
!=====END BLACS=====
call blacs_gridexit(icontxt)
call blacs_exit(0)

close(15,iostat=close_status) ! end read in
9998  FORMAT( 11(:,1X,F8.5) )
end

!+++++
!+++++SUBROUTINES+++++
!+++++

! convert global index to local index in block-cyclic distribution

subroutine g2l(i,n,np,nb,p,il)

implicit none
integer :: i ! global array index, input
integer :: n ! global array dimension, input
integer :: np ! processor array dimension, input
integer :: nb ! block size, input
integer :: p ! processor array index, output
integer :: il ! local array index, output
integer :: im1

im1 = i-1
p = mod((im1/nb),np)
il = (im1/(np*nb))*nb + mod(im1,nb) + 1

return
end
! convert local index to global index in block-cyclic distribution

subroutine l2g(il,p,n,np,nb,i)

implicit none
integer :: il ! local array index, input
integer :: p ! processor array index, input
integer :: n ! global array dimension, input
integer :: np ! processor array dimension, input
integer :: nb ! block size, input
integer :: i ! global array index, output
integer :: ilm1

ilm1 = il-1
i = (((ilm1/nb) * np) + p)*nb + mod(ilm1,nb) + 1

return
end

```

## Appendix III : MYPDGEMM and MYPDSYEV DFTB Subroutines

```

! PDGEMM Subroutine for global matrices AB=C
  subroutine MYPDGEMM(n,nb,mb,icontxt,prow,pcol,myrow,mycol, A, B, C)

  implicit none
  integer :: n      ! leading dimension of global matrices--INPUT
  real*8, dimension(n,n) :: A,B ! global matrices to be multiplied--INPUT
  real*8, dimension(n,n) :: C   ! global product matrix--OUTPUT
  integer :: icontxt, prow,pcol,myrow, mycol ! blacs data--INPUT
  integer :: nb, mb      ! problem size and block size
  integer :: myunit      ! local output unit number
  integer :: myArows, myAcols ! size of local subset of global array
  integer :: i,j, igrd,jgrd, iproc,jproc, myi,myj, p !navigating variables
  integer :: numroc      ! blacs routine
  integer :: info        ! scalapack return value
!
  integer :: open_status, close_status
  integer, dimension(9) :: ides_a, ides_b, ides_c ! scalapack array desc
  real*8, dimension(:,:), allocatable :: myA,myB,myC ! local matrices

!
!   prow = 2 ! number of process rows
!   pcol = 2 ! number of process columns
!   mb   = 6 ! number of columns in block
!   nb   = 6 ! number of rows in block
!=====INITIALIZING GLOBAL MATRICES=====
!
!   allocate (A(N,N))
!   allocate (B(N,N))
!   allocate (C(N,N))

!=====INITIALIZE PROCESS GRID=====
!
!   write(*,*)'... entering mypdgemm' ; call flush(6)
!   call blacs_pinfo (me,procs)
!   write(*,*)' ok -1, me:',me; call flush(6)
!   call blacs_get (0, 0, icontxt)
!   write(*,*)' ok -2, me:',me; call flush(6)
!   write(*,*)'icontxt:',icontxt,'me',me; call flush(6)
!   call blacs_gridinit(icontxt, 'R', prow, pcol)
!   write(*,*)' ok -3, me:',me; call flush(6)
!   call blacs_gridinfo(icontxt, prow, pcol, myrow, mycol)
!   write(*,*)' ok -4, me:',me; call flush(6)

!
!   myunit = 10+me
!   process grid info check
!   write(myunit,*)"-----"
!   write(myunit,*)"Output for processor ",me," to unit ",myunit
!   write(myunit,*)"Proc ",me,": myrow, mycol in p-array is ", &
!     myrow, mycol
!   flush(myunit)

! global structure:  matrix A of n rows and n columns
!                   matrix B of n rows and n column
!                   matrix C of n rows and n column

!
!   determining size of local array
  myArows = numroc(n, nb, myrow, 0, prow)
  myAcols = numroc(n, nb, mycol, 0, pcol)
!
!   process grid info check
!   write(myunit,*)"Size of global array is ",n," x ",n
!   write(myunit,*)"Size of block is      ",nb," x ",nb
!   write(myunit,*)"Size of local array is ",myArows," x ",myAcols
!   flush(myunit)

```



```

!=====GLOBAL MATRIX CHECK=====
!   if (myunit.eq.10) then   ! Initialize to have only one process print
!     write(myunit,*)"--- matrix check -----"
!     write(myunit,*) 'Matrix', A
!     do i = 1,n
!       write(myunit,9998) (A(i,j), j=1,n)
!     end do
!     write(myunit,*)
!     write(myunit,*) 'Matrix', B
!     do i = 1,n
!       write(myunit,9998) (B(i,j), j=1,n)
!     end do
!     write(myunit,*)
!   end if

!=====INITIALIZING LOCAL ARRAYS=====
!   write(myunit,*)"--- matrix check all   all   -----"
!   allocate(myA(myArows,myAcols))
!   write(*,*) "mya: ", allocated(myA)
!   allocate(myB(myArows,myAcols))
!   write(*,*)
!   allocate(myC(myArows,myAcols))

!   write(myunit,*)"--- before MM -----"
!   do i=1,n
!     call g2l(i,n,prow,nb,iproc,myi) ! see subroutines
!     if (myrow==iproc) then
!       do j=1,n
!         call g2l(j,n,pcol,nb,jproc,myj)
!         if (mycol==jproc) then
!           myA(myi,myj) = A(i,j)
!           myB(myi,myj) = B(i,j)
!           myC(myi,myj) = C(i,j)
!           check matrix filling
!           write(myunit,*)"A(",i,",",j,")", &
!             " --> myA(",myi,",",myj,")=",myA(myi,myj), &
!             "on proc(",iproc,",",jproc,")"
!           write(myunit,*)"B(",i,",",j,")", &
!             " --> myB(",myi,",",myj,")=",myB(myi,myj), &
!             "on proc(",iproc,",",jproc,")"
!           write(myunit,*)"C(",i,",",j,")", &
!             " --> myC(",myi,",",myj,")=",myC(myi,myj), &
!             "on proc(",iproc,",",jproc,")"
!         end if
!       end do
!     end do
!   end do
!   flush(myunit)

!=====PREPARE ARRAY DESCRIPTORS FOR SCLAPACK=====
!   ides_a(1) = 1      ! descriptor type
!   ides_a(2) = icontxt ! blacs context
!   ides_a(3) = n      ! global number of rows
!   ides_a(4) = n      ! global number of columns
!   ides_a(5) = nb     ! row block size
!   ides_a(6) = nb     ! column block size
!   ides_a(7) = 0      ! initial process row
!   ides_a(8) = 0      ! initial process column
!   ides_a(9) = myArows ! leading dimension of local array
!   assigning descriptors to all local matrices
!   do i=1,9
!     ides_b(i) = ides_a(i)
!     ides_c(i) = ides_a(i)

```

```

end do

!=====SCALAPACK ROUTINE=====
call pdgemm('N','N',n,n,n,1.0d0, myA,1,1,ides_a, &
           myB,1,1,ides_b,0.d0, &
           myC,1,1,ides_c )

! Print results
!   write(myunit,*)"--- after MM -----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi)
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        C(i,j) = myC(myi,myj)
        write(myunit,*)"A(",i,",",j,")", &
              " --> myA(",myi,",",myj,")=",myA(myi,myj), &
              "on proc(",iproc,",",jproc,")"
        write(myunit,*)"B(",i,",",j,")", &
              " --> myB(",myi,",",myj,")=",myB(myi,myj), &
              "on proc(",iproc,",",jproc,")"
        write(myunit,*)"C(",i,",",j,")", &
              " --> myC(",myi,",",myj,")=",myC(myi,myj), &
              "on proc(",iproc,",",jproc,")"
      end if
    end do
  end if
end do
flush(myunit)

!   write(myunit,*)
!   write(myunit,*) 'Matrix', C
!   do i = 1,n
!     write(myunit,9998) (C(i,j), j=1,n)
!   end do
!=====DEALLOCATE ALL MATRICES=====
deallocate(myA, myB, myC)
!   deallocate(A, B, C)
!   close(15,iostat=close_status) !close read in
!=====END BLACS=====
!   call blacs_gridexit(icontxt)
!   call blacs_exit(0)
9998   FORMAT( 11(:,1X,F8.5) )
end subroutine
!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!

subroutine MYPDSYEV(n,nb,mb,icontxt,prow,pcol,myrow,mycol,A,W)

implicit none
integer :: n          ! leading dimension of global matrix--INPUT
real*8, dimension(n,n) :: A ! global matrix to be solved--INPUT
real*8, dimension(n) :: W ! eigenvalues--OUTPUT
!   real*8, dimension(n,n) :: Z ! eigenvectors--OUTPUT
integer :: nb,mb      ! problem size and block size
integer :: myunit     ! local output unit number
integer :: myArows, myAcols ! size of local subset of global array
integer :: i,j, igrd,jgrd, iproc,jproc, myi,myj, p !navigating variables
integer :: numroc     ! blacs routine
integer :: me, procs, icontxt, prow, pcol, myrow, mycol ! blacs data
integer :: info       ! scalapack return value
integer :: lwork

!   integer open_status, close_status ! read in variables
integer, dimension(9) :: ides_a, ides_z ! scalapack array desc

```

```

real*8, dimension(:), allocatable :: work ! work array
real*8, dimension(:, :), allocatable :: myA, myZ ! local matrices
! write(*,*) '*****IN MYPDSYEV*****'
!   prow = 1 ! number of process rows
!   pcol = 1 ! number of process columns
!   nb = 1 ! leading dimension of block size
!   lwork = -1 ! returns idealized workspace
lwork = -1 ! allows first PDSYEV call to return proper work dimension

! determining size of local array
myArows = numroc(n, nb, myrow, 0, prow)
myAcols = numroc(n, nb, mycol, 0, pcol)
!=====INITIALIZING LOCAL ARRAYS=====
allocate(myA(myArows,myAcols))
allocate(myZ(myArows,myAcols))
allocate(work(1))
! write(myunit,*)"--- before operation ----"
do i=1,n
  call g2l(i,n,prow,nb,iproc,myi) ! see subroutines
  if (myrow==iproc) then
    do j=1,n
      call g2l(j,n,pcol,nb,jproc,myj)
      if (mycol==jproc) then
        myA(myi,myj) = A(i,j)
        myZ(myi,myj) = 0.0d0
! check matrix filling
! write(myunit,*)"A(",i,",",j,")", &
! " --> myA(",myi,",",myj,")=",myA(myi,myj), &
! "on proc(",iproc,",",jproc,")"
! write(myunit,*)"Z(",i,",",j,")", &
! " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
! "on proc(",iproc,",",jproc,")"
      endif
    enddo
  endif
enddo
flush(myunit)
! write(*,*) 'MATRICES DISTRIBUTED'
!=====PREPARE ARRAY DESCRIPTORS FOR SCLAPACK=====
ides_a(1) = 1 ! descriptor type
ides_a(2) = icontxt ! blacs context
ides_a(3) = n ! global number of rows
ides_a(4) = n ! global number of columns
ides_a(5) = nb ! row block size
ides_a(6) = nb ! column block size
ides_a(7) = 0 ! initial process row
ides_a(8) = 0 ! initial process column
ides_a(9) = myArows ! leading dimension of local array
! assigning descriptors to all local matrices
do i=1,9
  ides_z(i) = ides_a(i)
enddo
! write(myunit,*) 'descriptor arrays assigned'

!=====SCALAPACK ROUTINE=====
! write(myunit,*)'Made it to PDSYEV'
! flush(myunit)
! First call is to obtain dimension for work
! write(*,*) 'First Call'
call pdsyev('V','U',n,mya,1,1,ides_a,w,myZ,1,1,ides_z,work,lwork,info)
! write(myunit,*) 'work is'
! write(myunit,9998) work
! flush(myunit)
! lwork = work(1)

```

```

!       write(*,*) 'lwork: ', lwork
deallocate(work)
allocate(work(lwork))
!       flush(myunit)
!       performing actual calculation
!       write(*,*) 'work reallocated'
call pdsyev('V','U',n,mya,1,1,ides_a,w,myZ,1,1,ides_z,work,lwork,info)
!       write(*,*) 'made it through second call'
!       write(myunit,*)'Completed PDSYEV'
!       print results
!!      do iproc=1,prow
!!      if (myrow==iproc) then
!!      do jproc=1,pcol
!!      if (mycol==jproc) then
!!      do myi=1,myArows
!       call l2g(myi,iproc,n,prow,nb,i)
do i=1,n
call g2l(i,n,prow,nb,iproc,myi)
if (myrow==iproc) then
!!      do myj=1,myAcols
!!      call l2g(myj,jproc,n,pcol,nb,j)
do j=1,n
call g2l(j,n,pcol,nb,jproc,myj)
if (mycol==jproc) then
A(i,j) = myZ(myi,myj)
!       write(myunit,*)"A(",i,",",j,")", &
!       " --> myA(",myi,",",myj,")=",myA(myi,myj), &
!       "on proc(",iproc,",",jproc,")"
!       write(*,*)"Z(",i,",",j,")", &
!       " --> myA(",myi,",",myj,")=",myZ(myi,myj), &
!       "on proc(",iproc,",",jproc,")"
endif
enddo
endif
enddo
end if
!!      end do
!!      end if
!!      end do
flush(myunit)

!       write(myunit,*)"--- eigen values -----"
!       write(myunit, 9998) w

!=====DEALLOCATE ALL MATRICES=====
deallocate(myA, myZ)
deallocate(A,W,Z)
!       close(15,iostat=close_status) ! close read in
!=====END BLACS=====
!       call blacs_gridexit(icontxt)
!       call blacs_exit(0)
9998   FORMAT( 11(:,1X,F8.5) )

end subroutine

```