

Vascular Fluid Structure Simulation



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Overview

This project is to simulate vascular flow in arteries. The vascular system is an important component for the human health and a computational model of blood flow could help diagnosis and treatment of health problems.

- Evaluates the stability of implemented solvers to handle fluid structure interaction problems
- Use continuous Galerkin finite element method
- Utilize DIEL to solve weak coupling equations

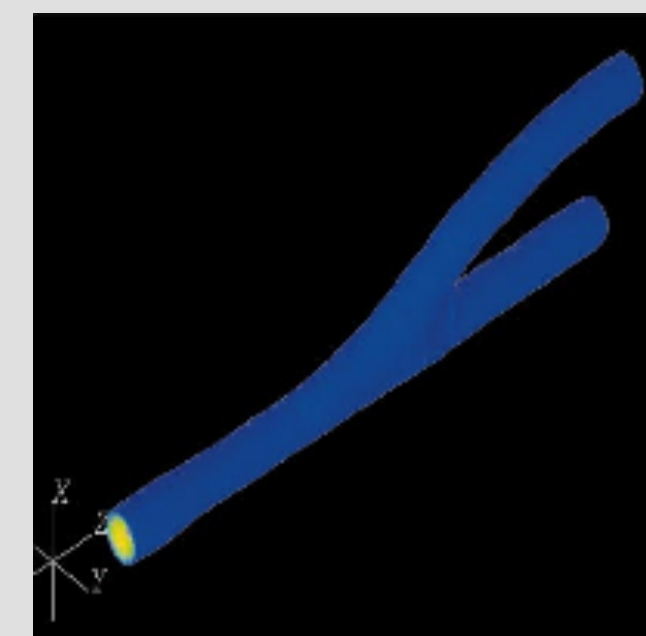
Fluid Structure Interaction

- Fluid Equations(INS)

$$\begin{cases} \mathbf{u}_t - \frac{1}{\text{Re}} \nabla^2 \mathbf{u} + \mathbf{u} \cdot \nabla \mathbf{u} + \nabla p = \mathbf{0} \\ \nabla \cdot \mathbf{u} = 0 \end{cases}$$

- Boundary Conditions

$$[u]_{r=a} = \frac{\partial \eta}{\partial t} \quad \text{and} \quad [w]_{r=a} = \frac{\partial \xi}{\partial t}$$



Quarteroni et al. [1]

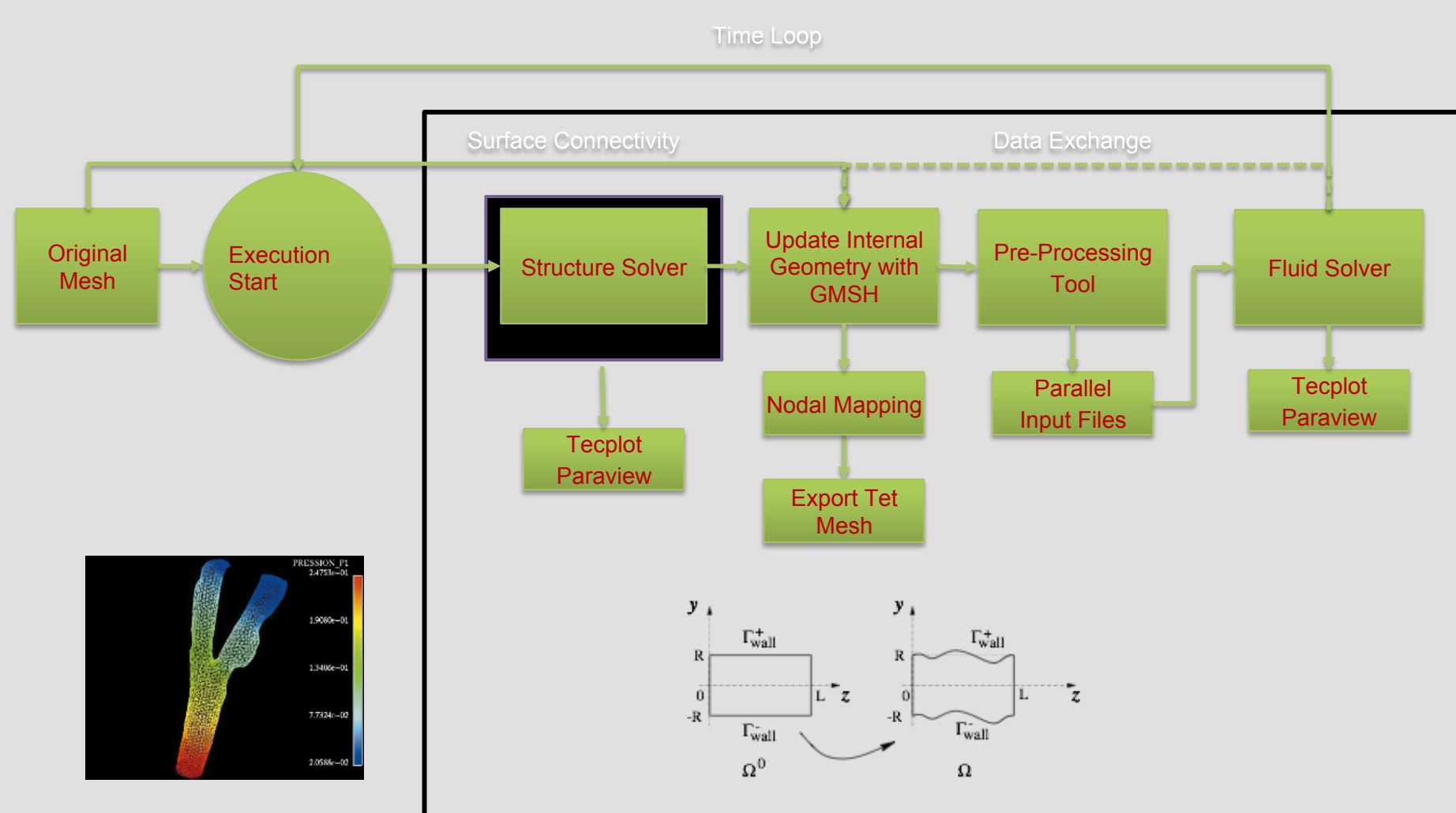
- Vessel Wall Equations(Structure Equations)

$$\begin{aligned} \nabla \cdot \boldsymbol{\tau}^s - \nabla p^s &= \mathbf{0}, \\ \det(\mathbf{F}) &= 1, \\ \boldsymbol{\tau}^s &= \mathbf{G}(\mathbf{F} \cdot \mathbf{F}^T - \mathbf{I}), \\ \mathbf{F} &= (\nabla_{\mathbf{x}} \boldsymbol{\chi})^T, \end{aligned}$$

- Solve Navier-Stokes equations(INS) for blood flow velocity and pressure
- Solve structure equations for radial and longitudinal deformations of the vessel wall
- Update the mesh
- Update radial velocity at vessel wall
- $t = t + \Delta t$
- Continue from Step 1

Parallel Computing, DIEL

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- Parallel Interoperable Computational Mechanics Simulation System (PICMSS)
- Each responsible for several rows of grid
- 1cm diameter x 6cm length



Methodology

To solve INS:

Parallel Interoperable Computational Mechanics System Simulator(PICMSS) was chosen to solve INS.

- PICMSS

- parallel computational software
- solving equations with continuous Galerkin finite element method
- C program with MPI
- uses Trilinos iterative library for solving systems of linear equations generated internally by finite element method.
- 2D triangle and quadrilateral, and 3D tetrahedron and hexahedron master elements.

fluid flow problems directly written in partial differential equation(PDE) template operator form

- Fihite Element Method

This method divides the domain into parts and over each parts, uses some element functions to seek approximate solution then assembles the parts.

$$\begin{aligned} \mathbf{u}(\mathbf{x}, r) &\approx \mathbf{u}^e(\mathbf{x}, r) = \sum_{j=1}^n U_j^e \psi_j^e(\mathbf{x}, r) \\ \int \psi_i^e \nabla^2 \mathbf{u} dV &= - \int \nabla \psi_i^e \cdot \nabla \mathbf{u} dV + \int \psi_i^e \cdot \nabla \mathbf{u} ds \\ &= - \{U_j^e\} \int \nabla \psi_i^e \cdot \nabla \psi_j^e dV + \int \psi_i^e \cdot \nabla \mathbf{u} ds \end{aligned}$$

In PDE template operator form:

$$[\nabla^2] \{u\} = - \{U_j^e\} \int \nabla \psi_i^e \cdot \nabla \psi_j^e dV = - \{b2kk\} \{U_j^e\}$$

x	x	x	x
x	x	x	x
x	x	x	x
x	x	x	x

To solve Structure Equations :

- Use continuous Galerkin finite element method
- Use Newmark method to solve system of second order PDE

-Newmark Method

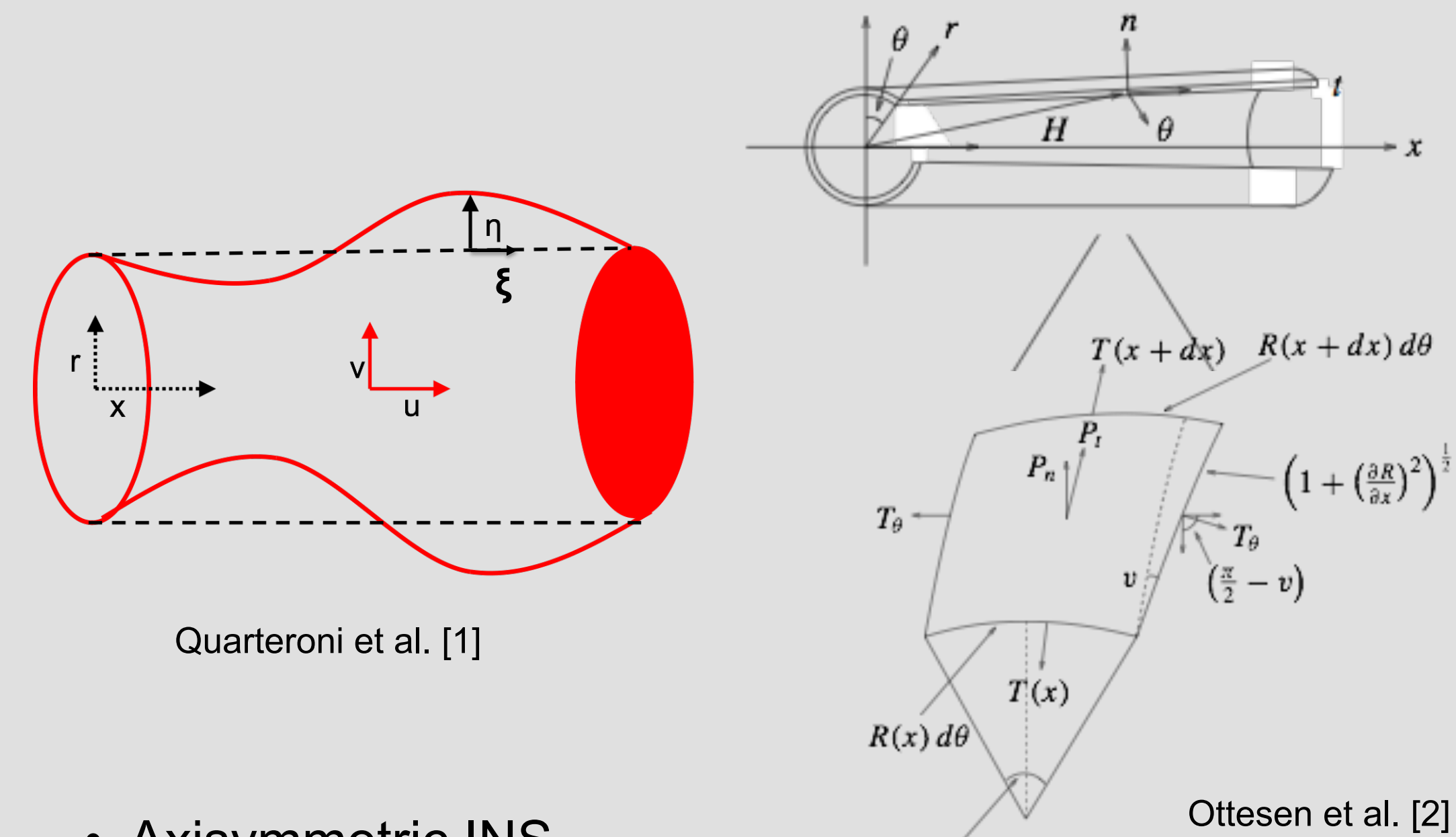
This method involves equations of the form:

$$[M] \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\} + [C] \left\{ \frac{\partial \eta}{\partial t} \right\} + [K] \{ \eta \} = F$$

The solution of this equation for the Newmark Method is :

$$\begin{aligned} & \left([M] + \frac{\delta t}{2} [C] + \frac{\delta t^2}{4} [K] \right) \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_{n+1} \\ &= [F]_{n+1} - [C] \left\{ \frac{\partial \eta}{\partial t} \right\}_n + \frac{\delta t}{2} \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_n - [K] \left\{ \eta \right\}_n + \delta t \left\{ \frac{\partial \eta}{\partial t} \right\}_n + \frac{\delta t^2}{4} \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_n \\ & \left\{ \eta \right\}_{n+1} = \left\{ \eta \right\}_n + \delta t \left\{ \frac{\partial \eta}{\partial t} \right\}_n + \frac{\delta t^2}{4} \left(\left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_n + \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_{n+1} \right) \\ & \left\{ \frac{\partial \eta}{\partial t} \right\}_{n+1} = \left\{ \frac{\partial \eta}{\partial t} \right\}_n + \frac{\delta t}{2} \left(\left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_n + \left\{ \frac{\partial^2 \eta}{\partial t^2} \right\}_{n+1} \right) \end{aligned}$$

1D structure and 2D axisymmetric Artery model



- Axisymmetric INS

$$\begin{aligned} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial r} + w \frac{\partial u}{\partial x} &= - \frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left(\frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{\partial^2 u}{\partial x^2} - \frac{u}{r^2} \right) \\ \frac{\partial w}{\partial t} + u \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial x} &= - \frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \left(\frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 w}{\partial x^2} \right) \\ \frac{1}{r} \frac{\partial}{\partial r} (r u) + \frac{\partial w}{\partial x} &= 0, \end{aligned}$$

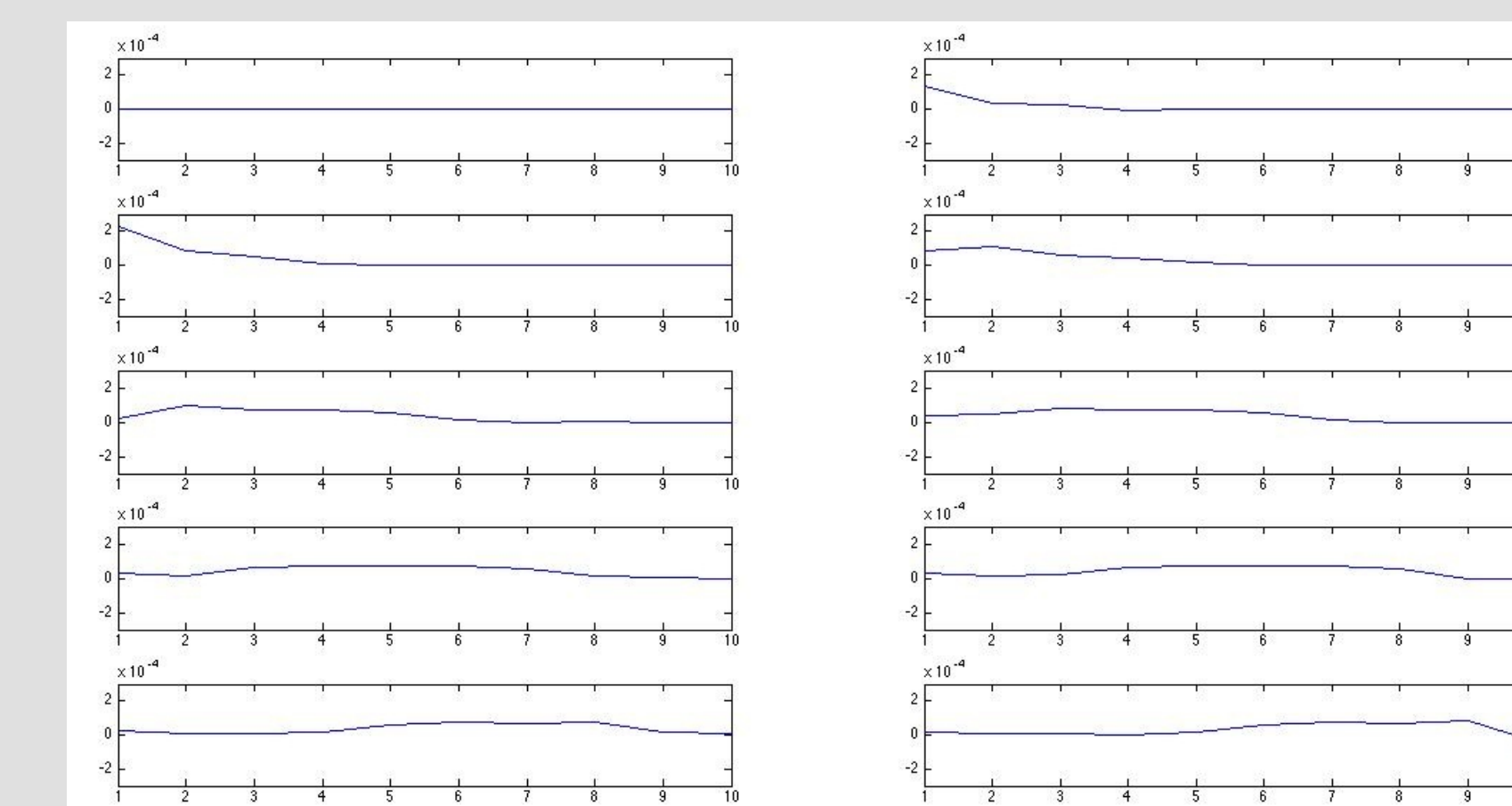
- 1D Structure Equations

$$\begin{aligned} M_0 \frac{\partial^2 \xi}{\partial t^2} + L_x \frac{\partial \xi}{\partial t} + K_x \xi \\ &= \frac{E_x h}{1 - \sigma_x \sigma_x} \frac{\partial^2 \xi}{\partial x^2} + \left(\frac{T_{i_0} - T_{\theta_0}}{a} - \frac{E_x h \sigma_x}{a(1 - \sigma_x \sigma_x)} \right) \frac{\partial \eta}{\partial x} - \mu \left[\frac{\partial w}{\partial r} + \frac{\partial u}{\partial x} \right]_s \\ M_0 \frac{\partial^2 \eta}{\partial t^2} + L_r \frac{\partial \eta}{\partial t} + K_r \eta \\ &= T_{i_0} \frac{\partial^2 \eta}{\partial x^2} + \left(\frac{T_{\theta_0}}{a^2} - \frac{E_0 h}{a^2(1 - \sigma_x \sigma_x)} \right) \eta + \frac{E_0 h \sigma_x}{a(1 - \sigma_x \sigma_x)} \frac{\partial \xi}{\partial x} + [p - 2\mu \frac{\partial u}{\partial r}]_s \end{aligned}$$

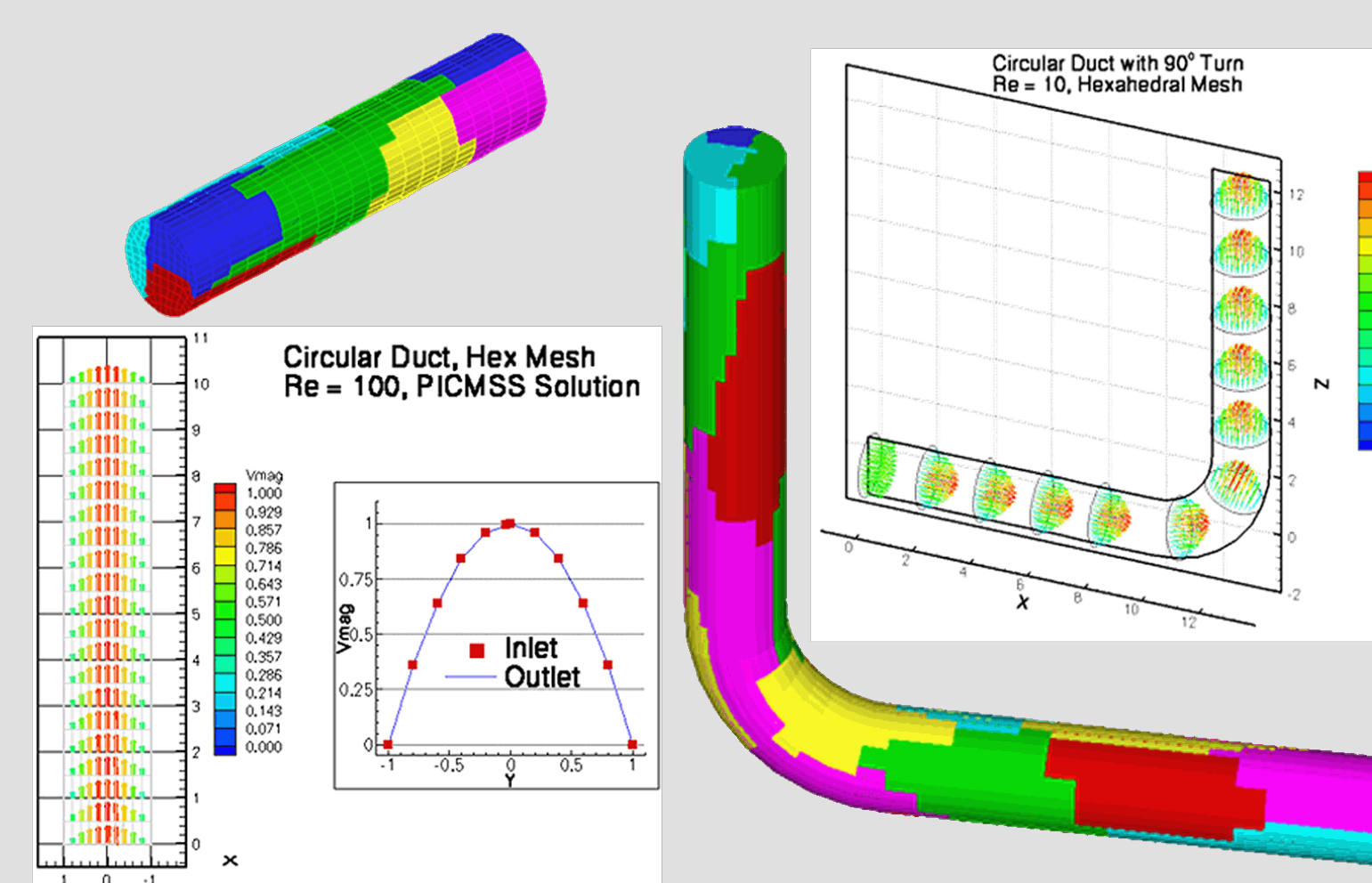
where E_i , $i = \theta, r$, is Young's modulus in the i th direction; h is the wall thickness; σ_x , $i = \theta, x$, is the Poisson ratio in the i th direction; and ϵ_i , $i = \theta, x$, is the displacement relative to the reference state;

Benchmark Results

- Benchmark result of 1D vessel wall



- Benchmark result of fluid equations



Future Work

- Run the code of 2D axisymmetric structure equations on PICMSS and compare with result of 1D serial code
- Solve full 3D fluid equations and structure equations
- Solve fully coupled fluid-structure equations
- Use DIEL to solve coupled equations

2D axisymmetric structure equations

- Simulate the vessel wall with no tangential velocity
 - Use the same structure equations on 3D mesh but the differences are boundary conditions (red circle)
- $$\begin{aligned} M_0 \frac{\partial^2 \xi}{\partial t^2} + L_x \frac{\partial \xi}{\partial t} + K_x \xi \\ &= \frac{E_x h}{1 - \sigma_x \sigma_x} \frac{\partial^2 \xi}{\partial x^2} + \left(\frac{T_{i_0} - T_{\theta_0}}{a} - \frac{E_x h \sigma_x}{a(1 - \sigma_x \sigma_x)} \right) \frac{\partial \eta}{\partial x} - \mu \left[\frac{\partial w}{\partial r} + \frac{\partial u}{\partial x} \right]_s \\ M_0 \frac{\partial^2 \eta}{\partial t^2} + L_r \frac{\partial \eta}{\partial t} + K_r \eta \\ &= T_{i_0} \frac{\partial^2 \eta}{\partial x^2} + \left(\frac{T_{\theta_0}}{a^2} - \frac{E_0 h}{a^2(1 - \sigma_x \sigma_x)} \right) \eta + \frac{E_0 h \sigma_x}{a(1 - \sigma_x \sigma_x)} \frac{\partial \xi}{\partial x} + [p - 2\mu \frac{\partial u}{\partial r}]_s \end{aligned}$$

Full 3D structure equations

D is the deformation matrix of vessel wall, and p is the pressure of the wall

$$\begin{aligned} \frac{\partial}{\partial x_1} (F_{11}^2 + F_{12}^2 - 1 - p) + \frac{\partial}{\partial x_2} (F_{21} F_{11} + F_{22} F_{12}) &= 0 \\ \frac{\partial}{\partial x_1} (F_{21} F_{11} + F_{22} F_{12}) + \frac{\partial}{\partial x_2} (F_{21}^2 + F_{22}^2 - 1 - p) &= 0 \end{aligned}$$

$$\begin{aligned} -\frac{\partial p}{\partial x_1} &= 0 \\ F_{11} F_{22} - F_{21} F_{12} &= 0 \\ F_{ij} &= \frac{\partial D_i}{\partial x_j} \end{aligned}$$

References

- A. Quarteroni, M. Tuveri, A. Veneziani, "Computational vascular fluid dynamics: problems, models, and methods", Comput Visual Sci, vol. 2, pp. 163-197, 2000.
- J. T. Ottesen, M. S. Olufsen, J. K. Larsen, Applied Mathematical Models in Human Physiology(Siam Monographs on Mathematical Modeling and Computation), SIAM, 2004.

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